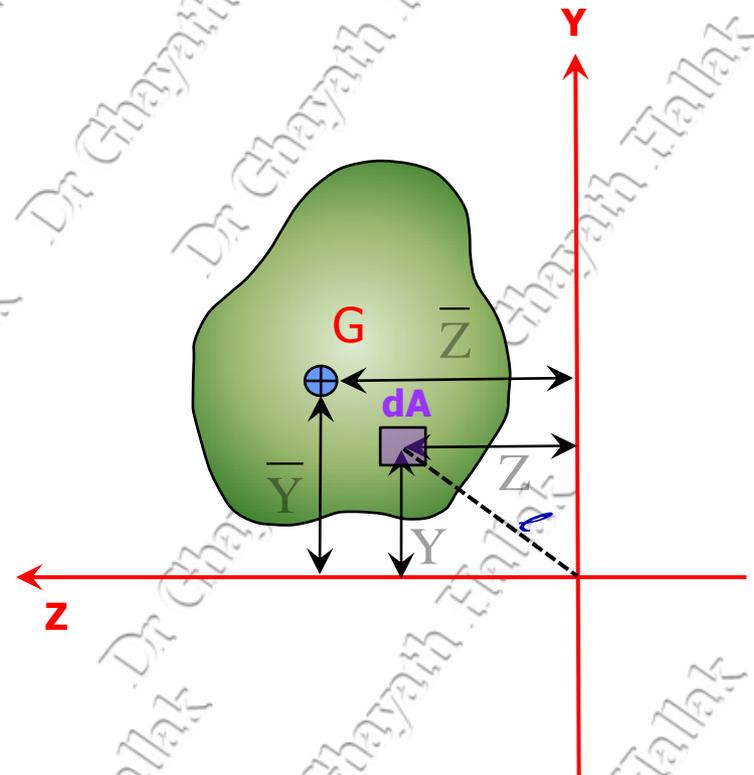


MOMENT OF INERTIA
The Second moment of area

1- The Second moment of area, The **MOMENT OF INERTIA**: (mm^4 , m^4)

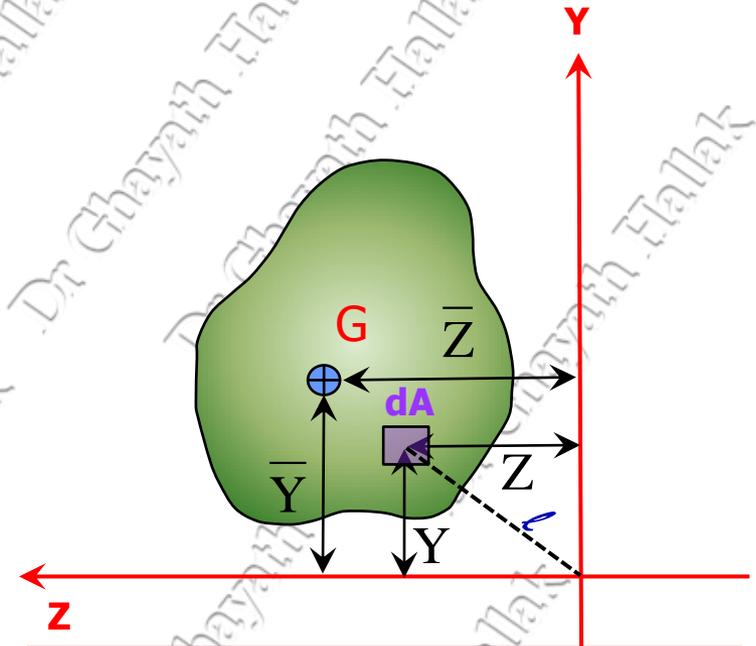
The **Moment of Inertia (I)** is a term used to describe the capacity of a cross-section to resist bending. It is always considered with respect to a reference axis such as Z or Y. It is a mathematical property of a section concerned with a surface area and how that area is distributed about the reference axis. The reference axis is usually a centroidal axis (**NOT "Y & Z" axes shown in the Fig**). The moment of Inertia expressed mathematically as: 



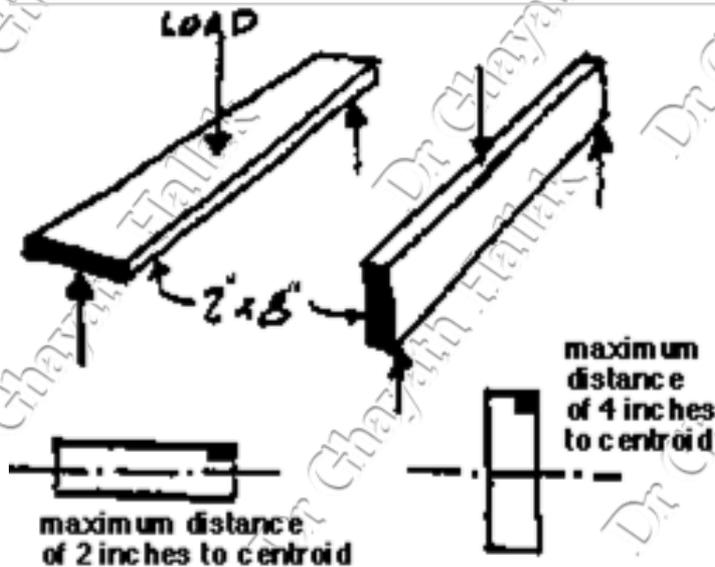
$$I_Z = \int_A Y^2 dA, I_Y = \int_A Z^2 dA$$

1- The Second moment of area, The **MOMENT OF INERTIA**: (mm⁴, m⁴)

The Moment of Inertia is an important value which is used to determine the state of stress in a section, to calculate the resistance to buckling, and to determine the amount of deflection in a beam.



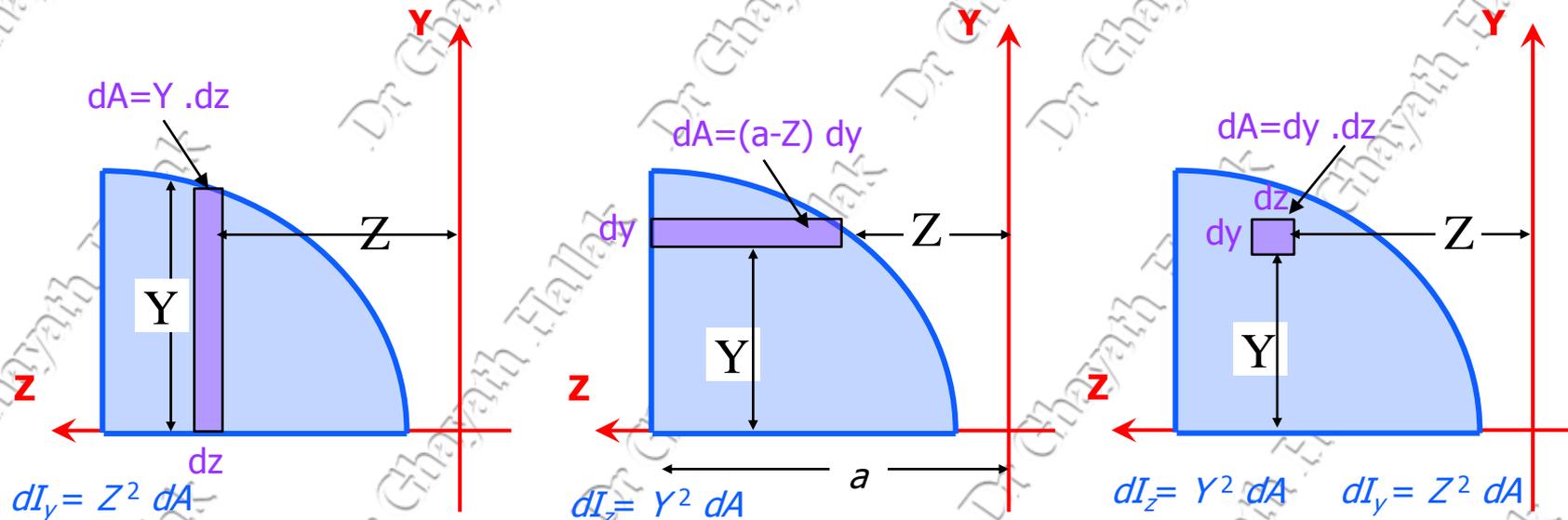
$$I_Z = \int_A Y^2 dA, \quad I_Y = \int_A Z^2 dA$$



Both boards have the same cross-sectional area, but the area is distributed differently about the horizontal centroidal axis.

1- The Second moment of area, The MOMENT OF INERTIA: (mm^4 , m^4)

DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION



The moment of inertia of an area is always positive

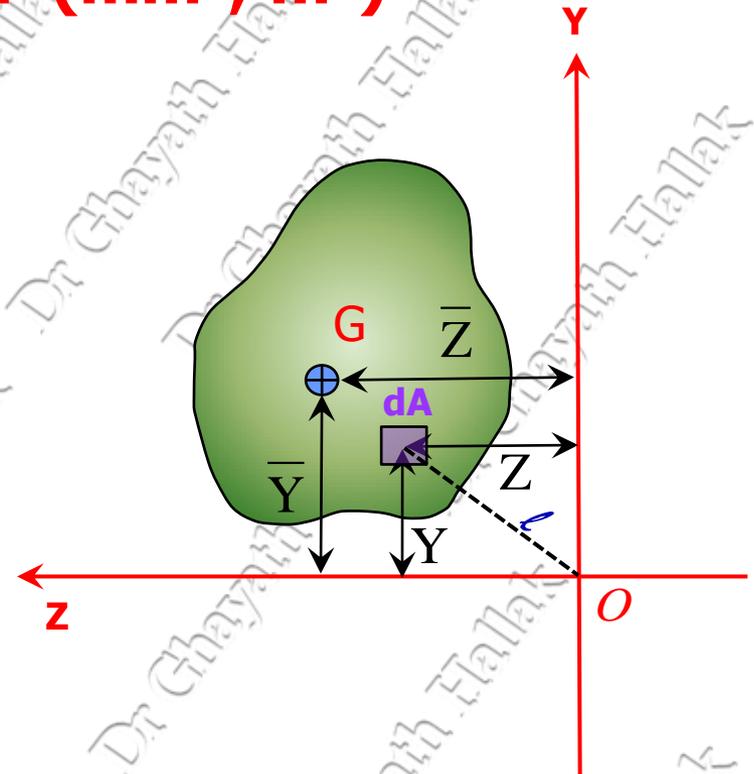
2- The polar moment of Inertia (mm^4, m^4)

Polar moment of inertia, denoted by J_o or I_p , is the area moment of inertia about the X -axis (perpendicular to plan of cross-section area) given by:

$$I_p = J_o = \int_A l^2 dA = \int_A (Z^2 + Y^2) dA$$

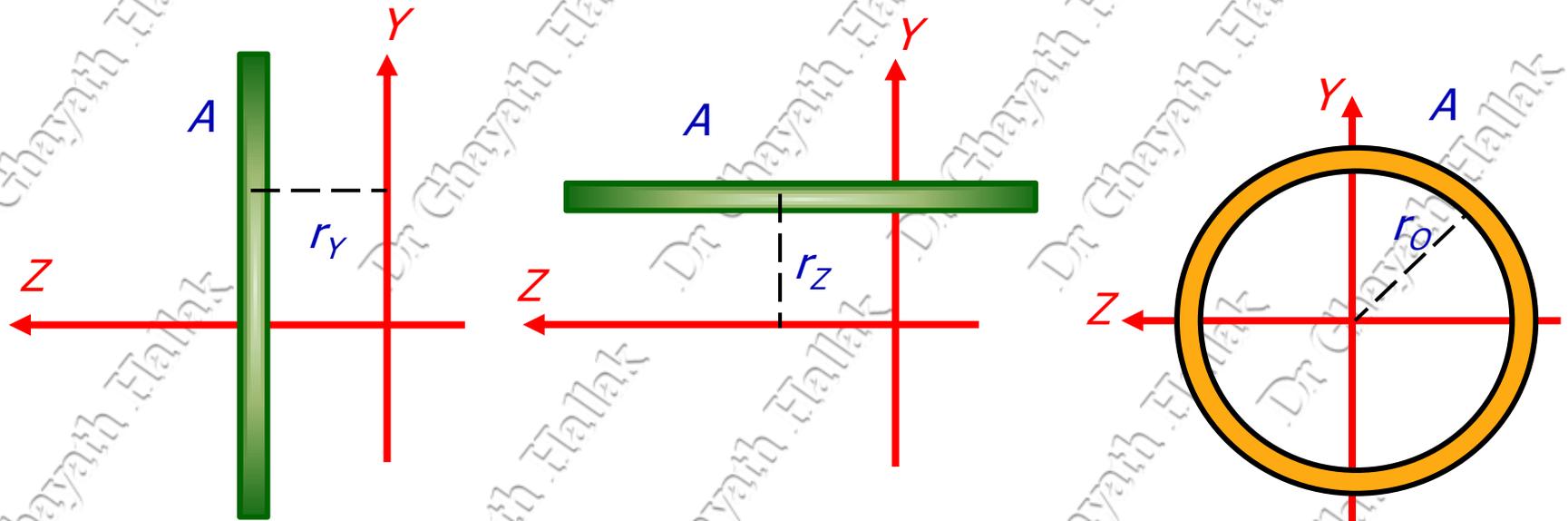
$$= \int_A Z^2 dA + \int_A Y^2 dA$$

$$I_p = J_o = I_Y + I_Z$$



This integral of great importance in problems concerning the torsion of cylindrical shafts and in problems dealing with the rotation of slabs

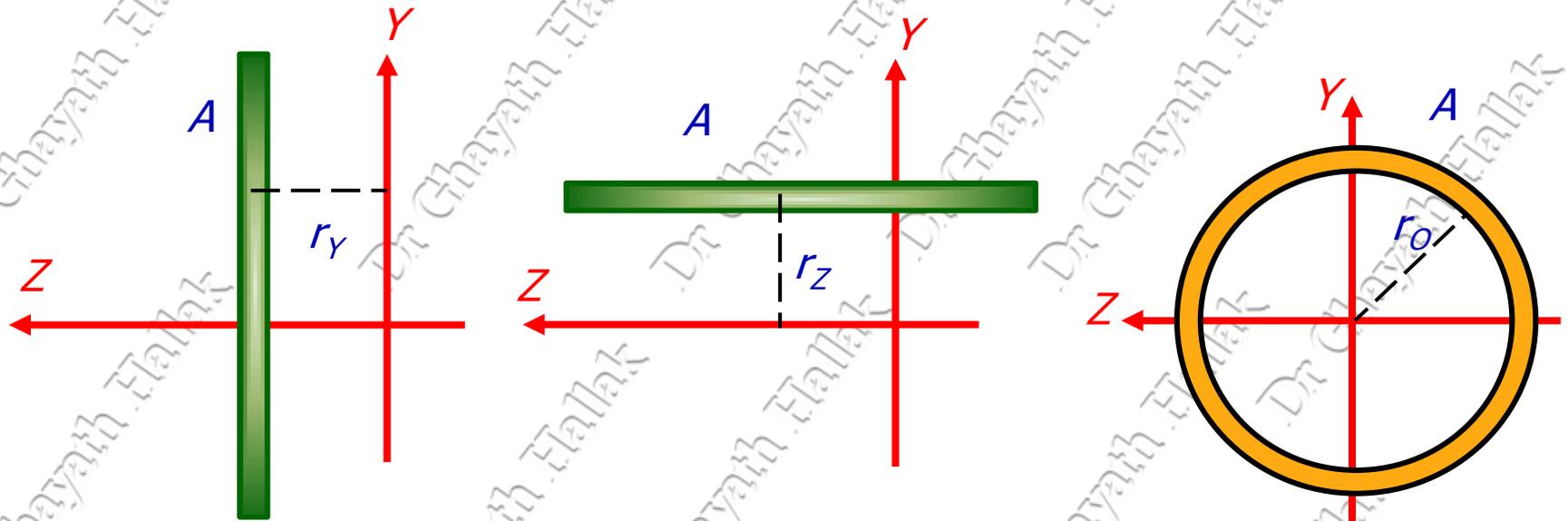
3- Radius of gyration (mm^3, m^3)



The **radius of gyration** is the distance r away from the axis that all the area can be concentrated to result in the same moment of inertia. That is,

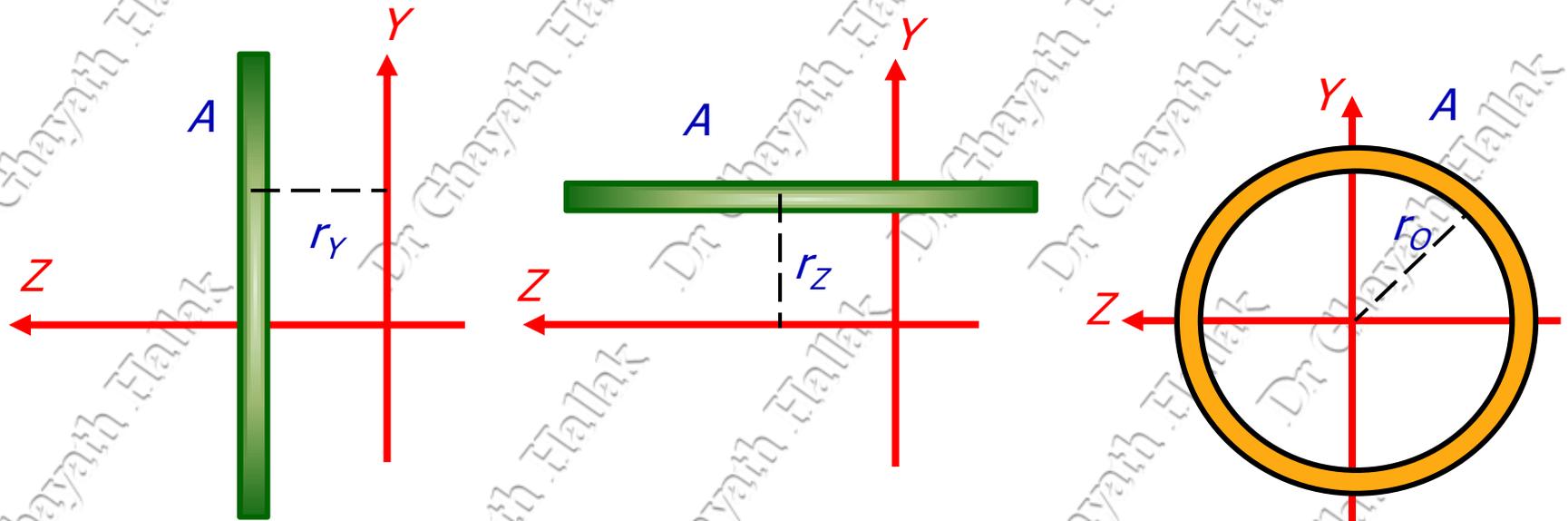
$$I = r^2 A = i^2 A$$

3- Radius of gyration (mm^3, m^3)



For a given area, one can define the radius of gyration around the Y -axis, denoted by r_Y , (i_Y) the radius of gyration around the Z -axis, denoted by r_Z , (i_Z) and the radius of gyration around the X -axis, denoted by r_O , (i_O). These are calculated from the relations:

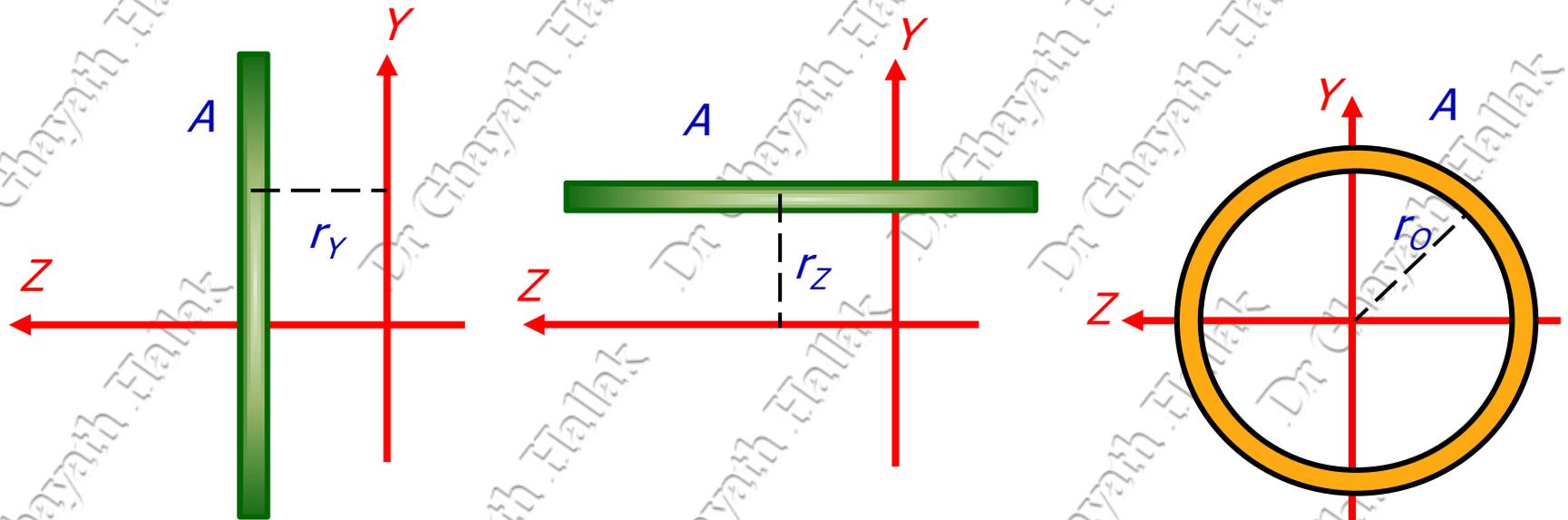
3- Radius of gyration (mm^3, m^3)



$$i_Z^2 = r_Z^2 = \frac{I_Z}{A}, \quad i_Y^2 = r_Y^2 = \frac{I_Y}{A}, \quad i_O^2 = r_O^2 = \frac{J_O}{A}$$

$$i_Z = r_Z = \sqrt{\frac{I_Z}{A}}, \quad i_Y = r_Y = \sqrt{\frac{I_Y}{A}}, \quad i_O = r_O = \sqrt{\frac{J_O}{A}}$$

3- Radius of gyration (mm^3, m^3)



It can easily to show from $J_O = I_Y + I_Z$ that

$$r_Z^2 + r_Y^2 = r_O^2$$

4- Product of Inertia (mm^4, m^4)

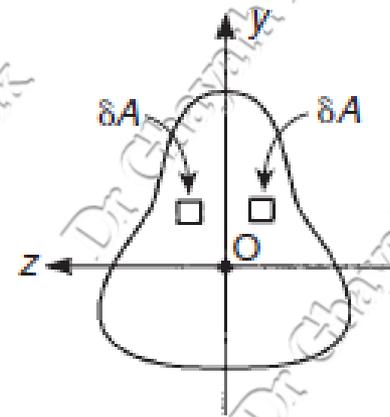
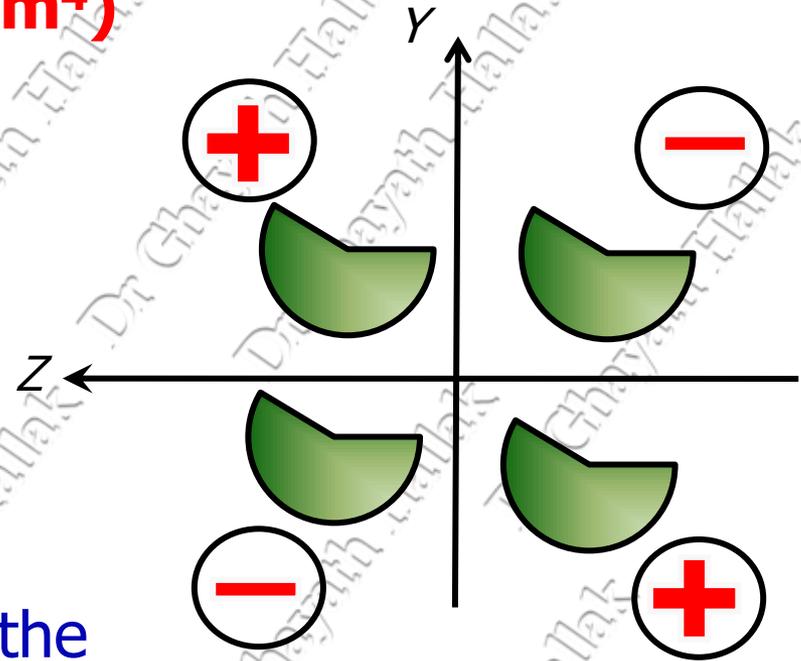
The product second moment of area, I_{zy} , of a beam section with respect to z and y axes is defined by:

$$I_{zy} = \int_A Z Y dA$$

when one (or both) of the coordinate axes is an axis of symmetry



$$I_{zy} = 0$$



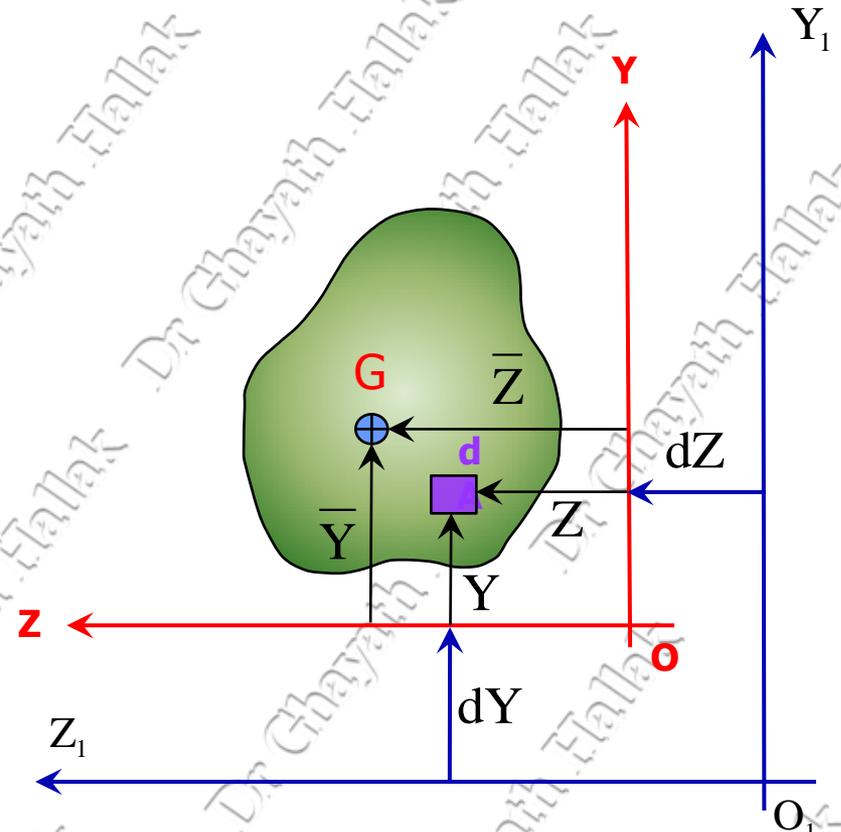
5- Parallel-Axis Theorems:

Suppose that we know the value of I_Y , I_Z and I_{YZ} . We need to determine the value of I_{Y_1} , I_{Z_1} and $I_{Y_1Z_1}$ (moment of Inertia according to the new axes Y_1 and Z_1 "parallel axis")

$$I_{Z_1} = \int_A Y_1^2 dA$$

$$I_{Z_1} = \int_A (Y + dY)^2 dA$$

$$I_{Z_1} = \int_A Y^2 dA + dY^2 \int_A dA + 2 dY \int_A Y dA$$



5- Parallel-Axis Theorems:

$$I_{Z_1} = I_Z + 2 dY Q_Z + dY^2 A$$

Similarly

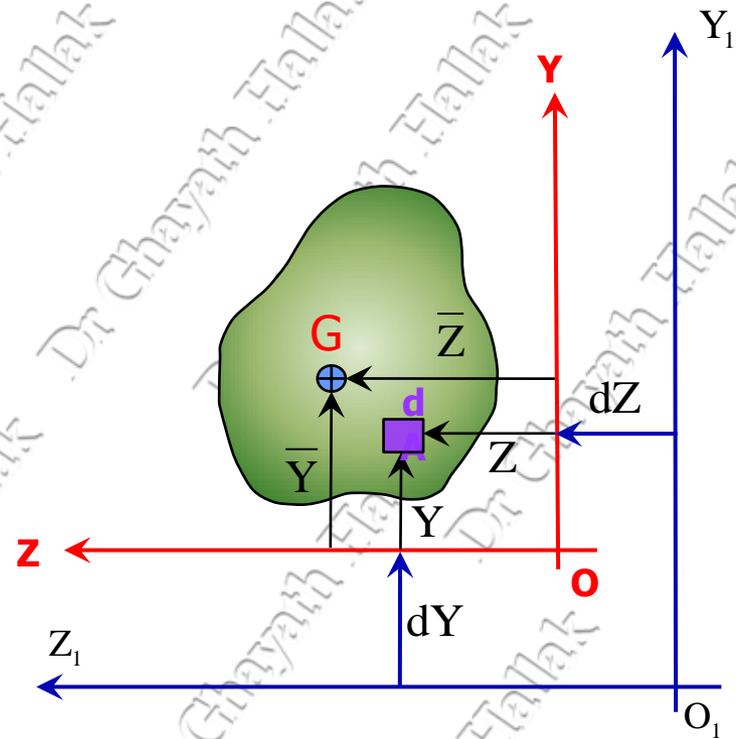
$$I_{Y_1} = I_Y + 2 dZ Q_Y + dZ^2 A$$

Product of Inertia

$$I_{Z_1 Y_1} = \int_A Y_1 Z_1 dA = \int_A (Y + dY) (Z + dZ) dA$$

$$I_{Z_1 Y_1} = \int_A Y Z dA + dY \int_A Z dA + dZ \int_A Y dA + dY dZ \int_A dA$$

$$I_{Z_1 Y_1} = I_{ZY} + dY Q_Y + dZ Q_Z + dY dZ A$$



5- Parallel-Axis Theorems:

IF Z & Y are CENTROIDAL axes

Then

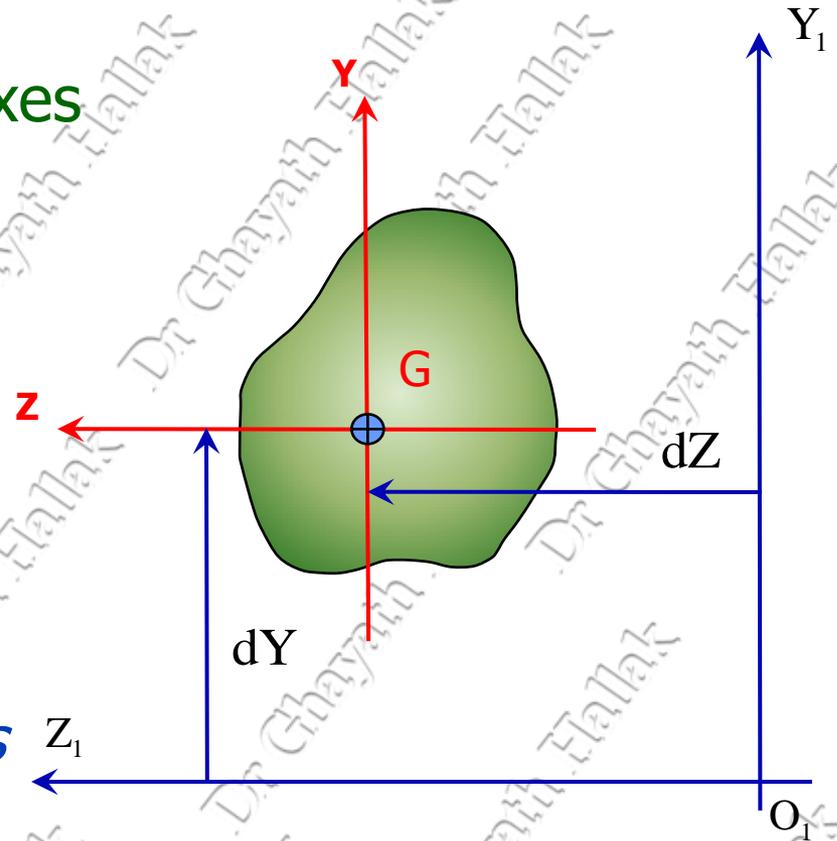
$$I_{Z1} = I_{GZ} + dY^2 A$$

$$I_{Y1} = I_{GY} + dZ^2 A$$

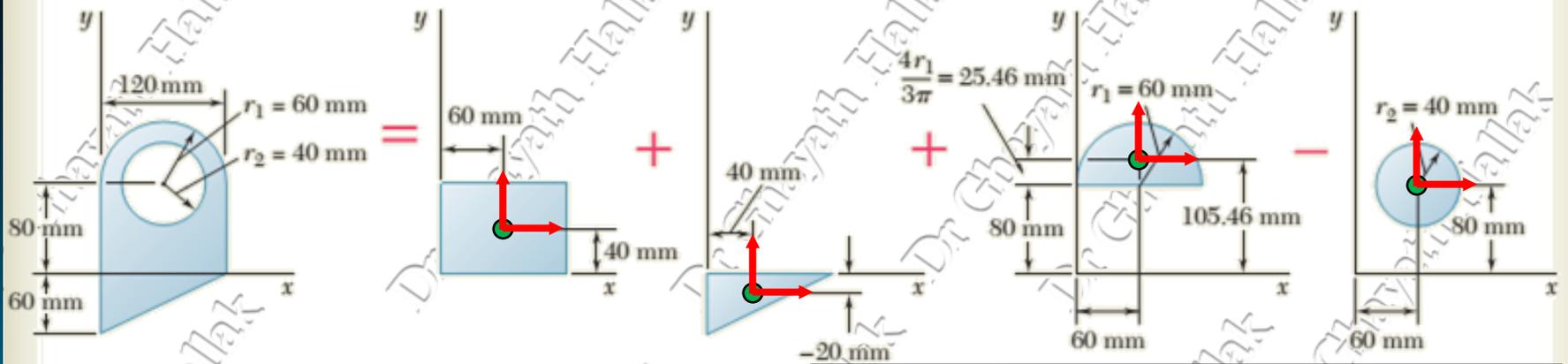
$$I_{Z1Y1} = I_{GZY} + dY dZ A$$

It can be seen from Eqs. above that if either GZ or GY is an axis of symmetry, i.e. $I_{GZY} = 0$, then $I_{Z1Y1} = dY dZ A$

Thus for a section component having an axis of symmetry that is parallel to either of the section reference axes the product second moment of area is the product of the coordinates of its centroid multiplied by its area.



5- MOMENTS OF INERTIA OF COMPOSITE AREAS



Rectangle		$\bar{I}_{x'} = \frac{1}{12}bh^3$ $\bar{I}_{y'} = \frac{1}{12}b^3h$ $I_x = \frac{1}{3}bh^3$ $I_y = \frac{1}{3}b^3h$ $J_C = \frac{1}{12}bh(b^2 + h^2)$
Triangle		$\bar{I}_{x'} = \frac{1}{36}bh^3$ $I_x = \frac{1}{12}bh^3$

Circle		$\bar{I}_x = \bar{I}_y = \frac{1}{4}\pi r^4$ $J_O = \frac{1}{2}\pi r^4$
Semicircle		$I_x = I_y = \frac{1}{8}\pi r^4$ $J_O = \frac{1}{4}\pi r^4$
Quarter circle		$I_x = I_y = \frac{1}{16}\pi r^4$ $J_O = \frac{1}{8}\pi r^4$

EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

Determine the moment of inertia for the rectangular area with respect to (a) the centroidal x' axis, (b) the centroidal x' axis, (c) the axis x_b passing through the base of the rectangular, and (d) the pole or z' axis perpendicular to the x' - y' plane and passing through the centroid C.

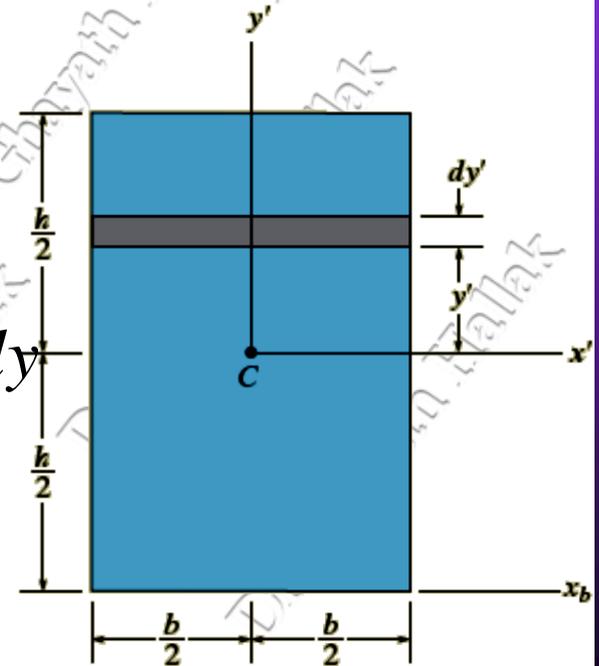
Part (a)

Differential element chosen, distance y' from x' axis.

Since $dA = b dy'$,

$$\bar{I}_x = \int_A y'^2 dA = \int_{-h/2}^{h/2} y'^2 (b dy') = b \int_{-h/2}^{h/2} y'^2 dy'$$

$$\bar{I}_x = b \left[\frac{y'^3}{3} \right]_{-h/2}^{+h/2} = \frac{1}{12} b h^3$$



EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

Part (b)

Differential element chosen, distance x' from y' axis.

Since $dA = h dx'$,

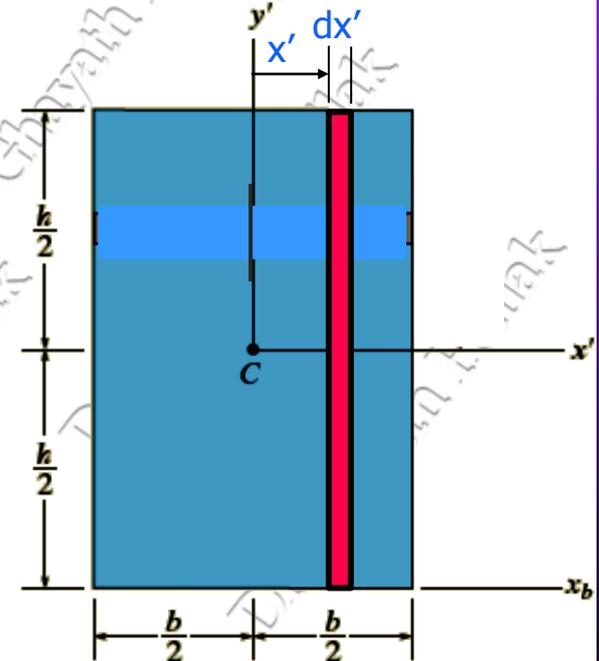
$$\bar{I}_y = \int_A x'^2 dA = \int_{-b/2}^{b/2} x'^2 (h dx') = h \int_{-b/2}^{b/2} x'^2 dy$$

$$\bar{I}_y = h \left[\frac{x'^3}{3} \right]_{-b/2}^{+b/2} = \frac{1}{12} hb^3$$

Part (c)

By applying parallel axis theorem,

$$I_{x_b} = \bar{I}_x + Ad^2 = \frac{1}{12} bh^3 + bh \left(\frac{h}{2} \right)^2 = \frac{1}{3} bh^3$$



EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

Part (d)

For polar moment of inertia about point C,

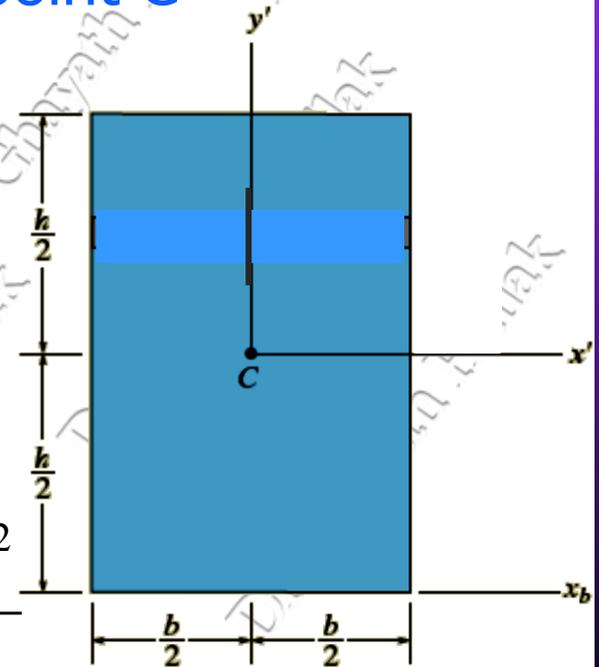
$$J_C = \bar{I}_{x'} + \bar{I}_{y'} = \frac{1}{12}bh(h^2 + b^2)$$

For radius of gyration about axis x' , y' & point C

$$r_{x'} = \sqrt{\frac{\bar{I}_{x'}}{A}} = \sqrt{\frac{bh^3/12}{bh}} = \frac{h}{2\sqrt{3}}$$

$$r_{y'} = \sqrt{\frac{\bar{I}_{y'}}{A}} = \sqrt{\frac{hb^3/12}{bh}} = \frac{b}{2\sqrt{3}}$$

$$r_C^2 = r_{z'}^2 = r_{x'}^2 + r_{y'}^2 = \frac{h^2}{12} + \frac{b^2}{12} = \frac{h^2 + b^2}{12}$$



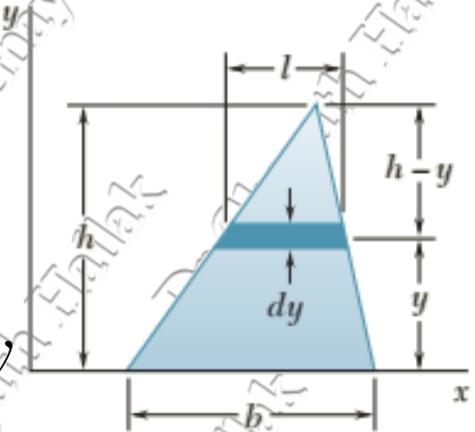
EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

Determine the moment of inertia of a triangle with respect to its base.

$$dI_x = y^2 dA, \quad dA = \ell dy$$

Using similar triangles, we have

$$\frac{l}{b} = \frac{h-y}{h} \Rightarrow l = b \frac{h-y}{h}, \quad \therefore dA = b \frac{h-y}{h} dy$$



$$I_x = \int y^2 dA = \int_0^h y^2 b \frac{h-y}{h} dy = \frac{b}{h} \int_0^h (hy^2 - y^3) dy$$

$$I_x = \frac{b}{h} \left[h \frac{y^3}{3} - \frac{y^4}{4} \right]_0^h = \frac{bh^3}{12}$$

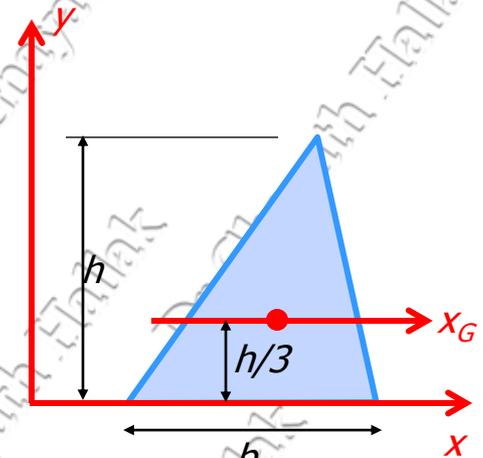
EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

Determine the moment of inertia for the area with respect to x_G axis

By applying parallel axis theorem,

$$I_x = \bar{I}_{xG} + Ad^2 \Rightarrow \bar{I}_{xG} = I_x - Ad^2$$

$$\bar{I}_{xG} = \frac{1}{12}bh^3 - \frac{bh}{2}\left(\frac{h}{3}\right)^2 = \frac{1}{36}bh^3$$



EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

(a) Determine the moment of inertia of a circular area with respect to a diameter.

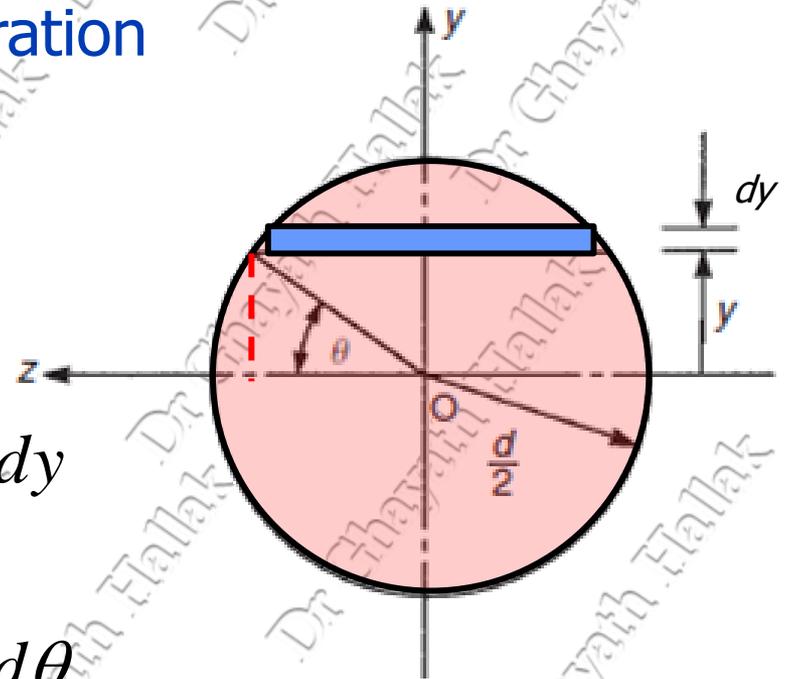
(b) Determine the centroidal polar moment of inertia of a circular area by direct integration

$$dA = 2 \left(\frac{d}{2} \cos \theta \right) dy$$

$$I_z = \int_A y^2 dA = \int_{-d/2}^{d/2} 2 \left(\frac{d}{2} \cos \theta \right) y^2 dy$$

$$y = \left(\frac{d}{2} \sin \theta \right) \Rightarrow dy = \left(\frac{d}{2} \cos \theta \right) d\theta$$

$$y = \mp d/2 \Rightarrow \theta = \mp \pi/2$$



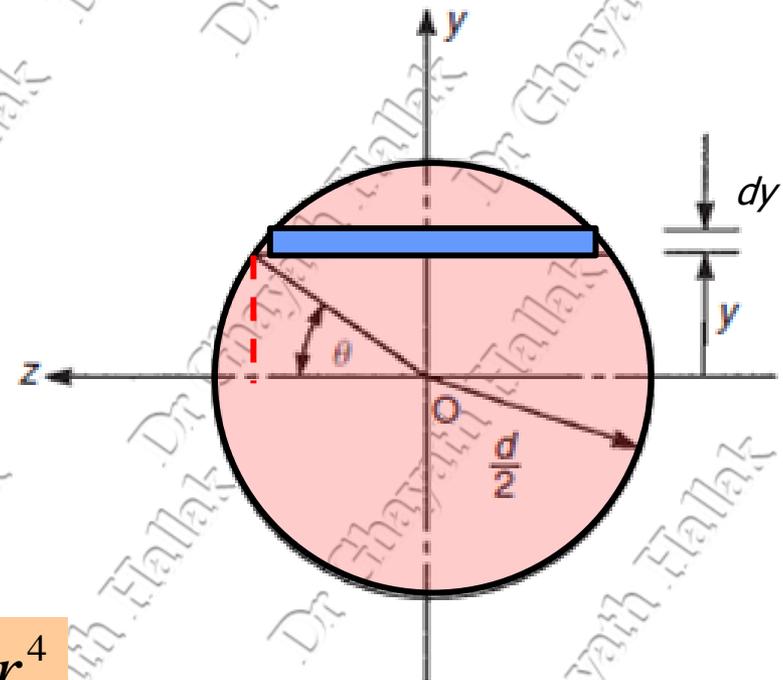
EXAMPLES- DETERMINATION OF THE MOMENT OF INERTIA OF AN AREA BY INTEGRATION

$$I_z = \int_{-\pi/2}^{\pi/2} (d \cos \theta) \left(\frac{d}{2} \sin \theta \right)^2 \left(\frac{d}{2} \cos \theta \right) d\theta$$

$$I_z = \frac{d^4}{8} \int_{-\pi/2}^{\pi/2} \cos^2 \theta \sin^2 \theta d\theta$$

$$\Rightarrow I_z = \frac{\pi d^4}{64} = I_y$$

$$\Rightarrow I_z = \frac{\pi r^4}{4} = I_y$$



$$J_O = I_z + I_y = \frac{\pi d^4}{32} = \frac{\pi r^4}{2}$$