

تصميم بمساعدة الحاسب
Computer Aided Design

Lecture 5

Optimization & Mathematical Programming

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Last Lecture

- Statistics
 - Graphics
- Regression and Curve Fitting
 - Linear
 - Higher order
 - Example
- Optimization
- Projectile Motion
 - Analytical solution
 - Numerical solution
- Other Examples
- Layout Optimization
 - <http://www.layopt.com/>

Content

- Mathematical Programming
 - Linear Programming
- Optimization Examples

Mathematical Programming

- Variables
 - Continuous, e.g. geometry
 - Discrete, e.g. section or material selection (integer, binary)
- Constraints
 - Linear vs. nonlinear
 - Equality vs. inequality
 - Objective function
 - Maximization, minimization
- Linear programming

Linear Programming

- Variables (n):

$$x_1, x_2, \dots, x_n$$

- Minimize:

$$f(x_1, x_2, \dots, x_n) = c_1x_1 + c_2x_2 + \dots + c_nx_n$$

- Constraints (m):

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

$$x_1, x_2, \dots, x_n \geq 0$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} \quad c = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

$$a = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}$$

Linear Programming

- Variables (n):

$$x$$

- Minimize:

$$f(x) = c^T x$$

- Constraints (m):

$$ax = b$$

$$x \geq 0$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} \quad c = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

$$a = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}$$

Linear Programming

- Minimization problem
- Maximize

$$f(x) = c^T x$$

Equivalent to minimize

$$-f(x) = -c^T x$$

- Objective value
Equivalent to minimizing error

Linear Programming

- Constraints:

- Equality:

$$a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n = b_i$$

- Inequality constraints:

- $a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n \leq b_i$

Equivalent to $a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n + x_{n+1} = b_i$

- $a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n \geq b_i$

Equivalent to $a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n - x_{n+1} = b_i$

Linear Programming

- Constraints:

$$x_i \geq 0$$

- For variables that could be negative:

$$x_i = x_i^+ - x_i^-$$

$$x_i^+, x_i^- \geq 0$$

Linear Programming

- Solution:
 - Solution vs. no solution
 - Single vs. multiple solutions
 - Bounded vs. unbounded solution

Linear Programming

Maximize:

$$z = c_1x + c_2y$$

Subject to:

$$a_1x + b_1y \leq d_1$$

$$a_2x + b_2y \leq d_2$$

$$x, y \geq 0$$

Maximize:

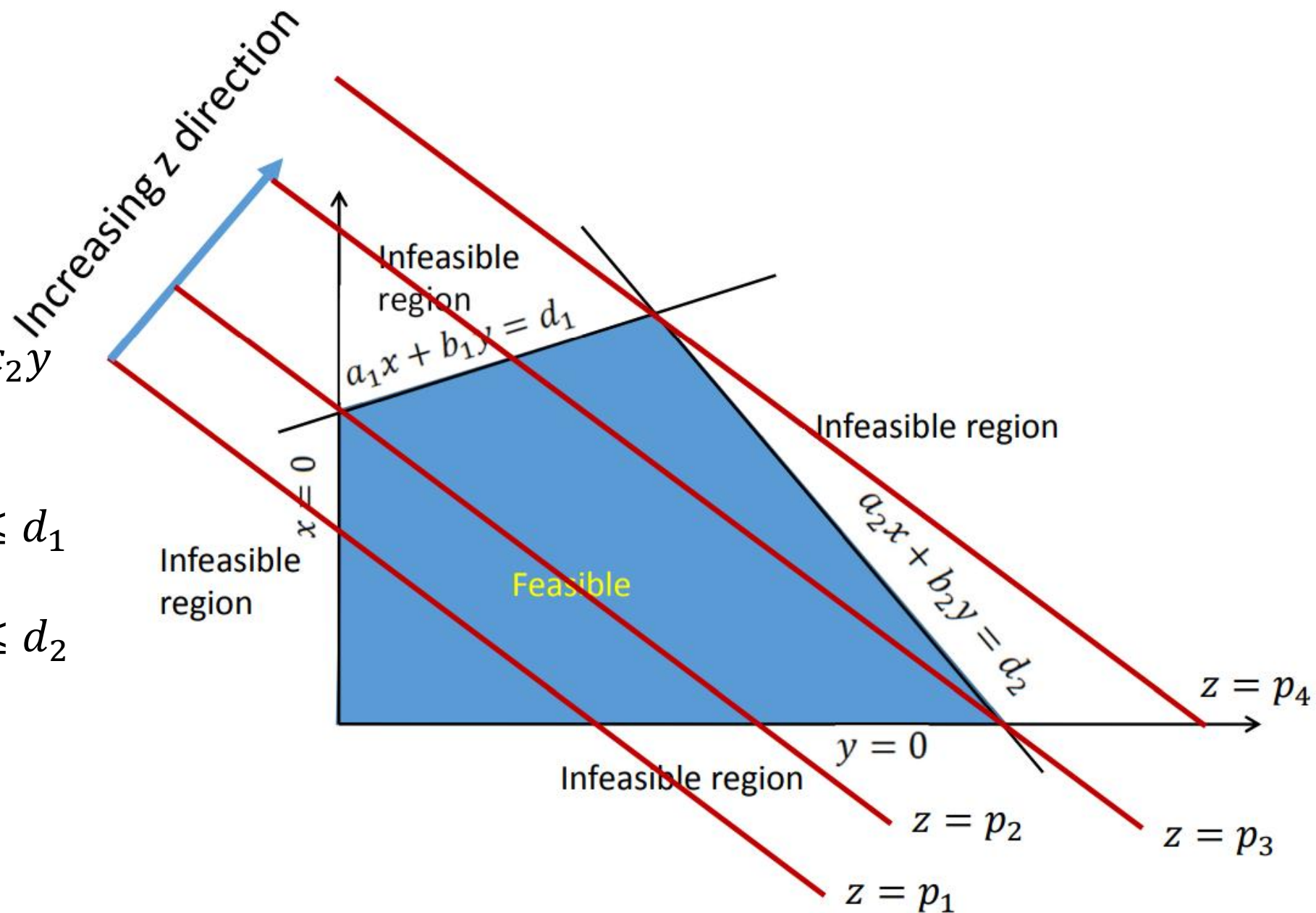
$$z = c_1x + c_2y$$

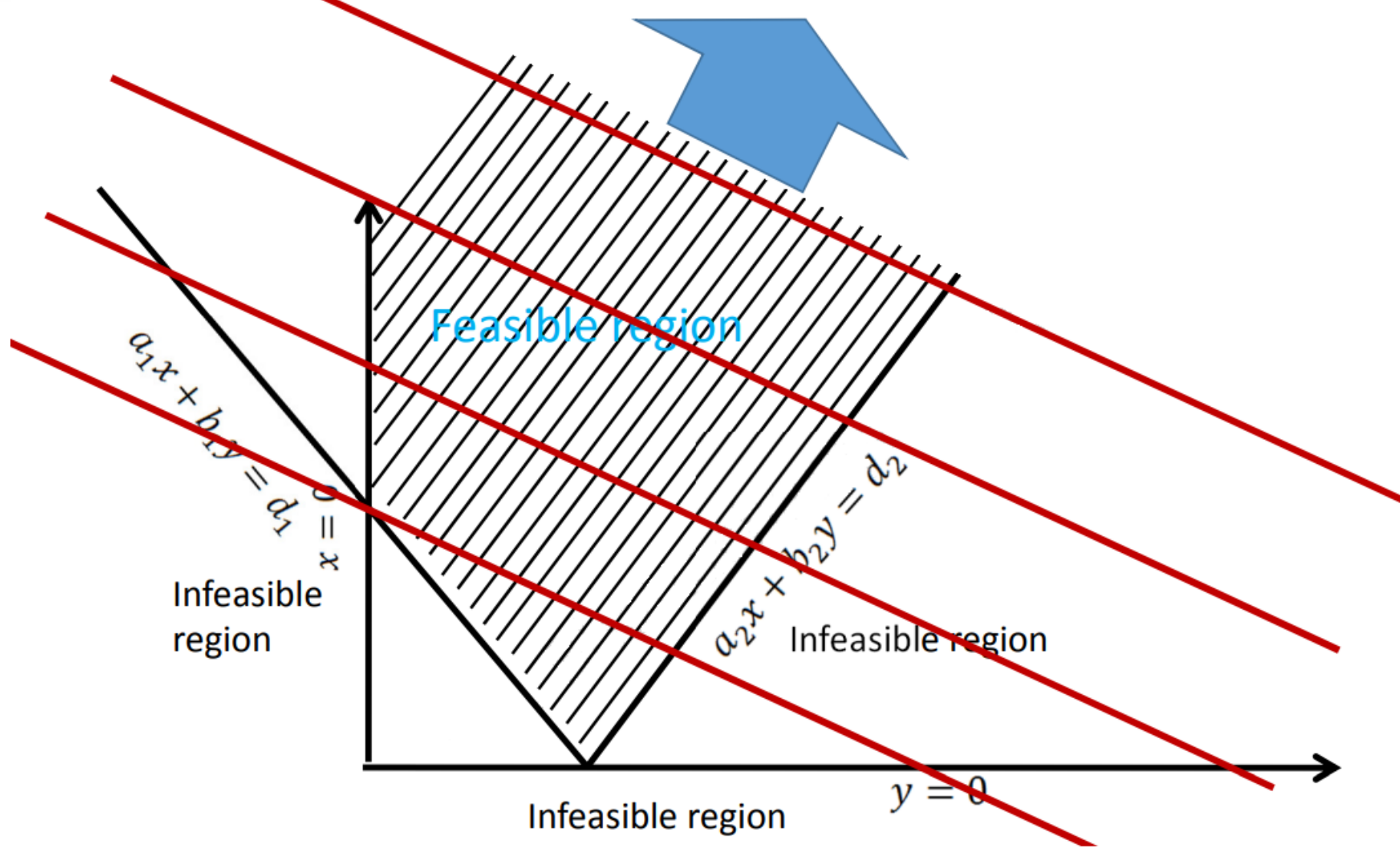
Subject to:

$$a_1x + b_1y \leq d_1$$

$$a_2x + b_2y \leq d_2$$

$$x, y \geq 0$$





Mathematical Programming

- Numerical examples

Example 1

- Maximize $f(x, y) = -x^2 + 10.x - y^2 + 8.y$

- Analytically:

$$\frac{\delta f(x, y)}{\delta x} = -2.x + 10 = 0$$

$$\frac{\delta f(x, y)}{\delta y} = -2.y + 8 = 0$$

$$x = 5$$

$$y = 4$$

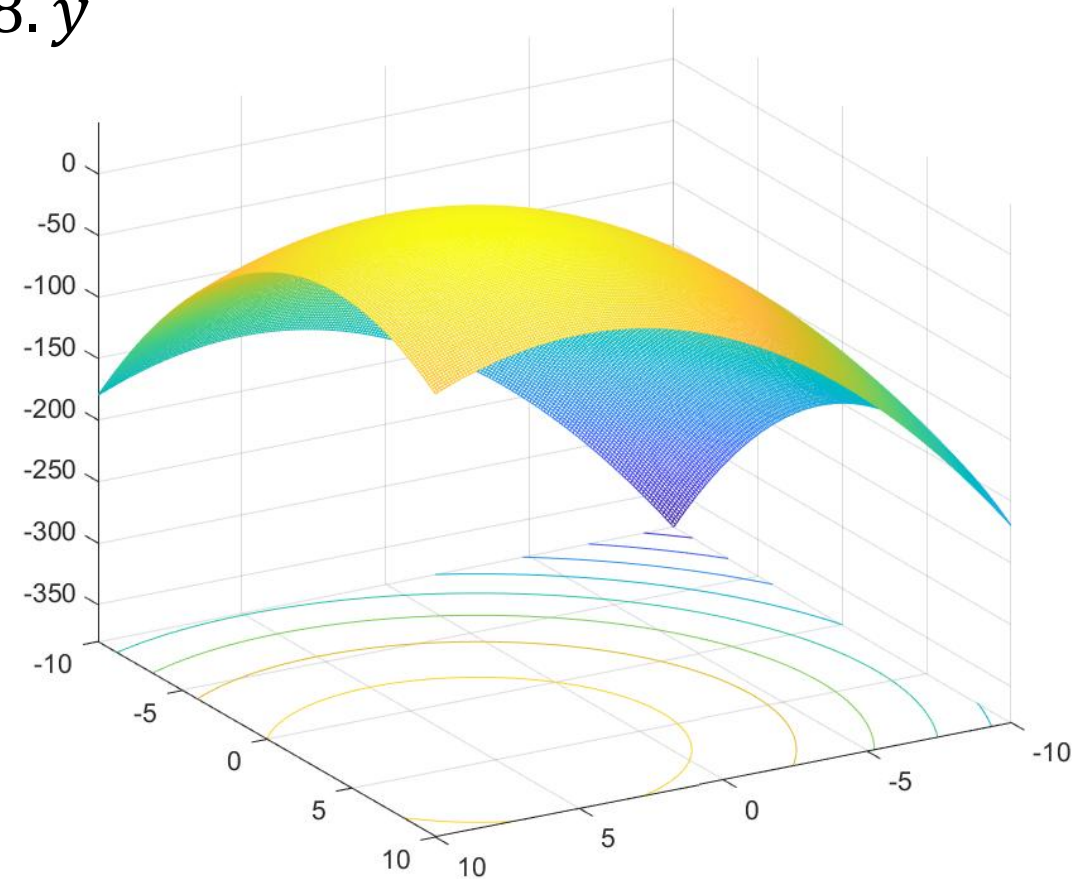
$$f(x, y) = 41$$

Example 1

- Maximize $f(x, y) = -x^2 + 10x - y^2 + 8y$

- Numerically:

```
[x, y] = meshgrid(0:0.1:10);  
f = -x.^2 + 10*x - y.^2 + 8*y;  
meshc(x, y, f)  
max(max(f))    % 41
```



Example 1

- Maximize $f(x, y) = -x^2 + 10x - y^2 + 8y$

- Symbolic:

```
f = @(x) -x(1).^2+10*x(1)-x(2).^2+8*x(2);
```

Minimization only

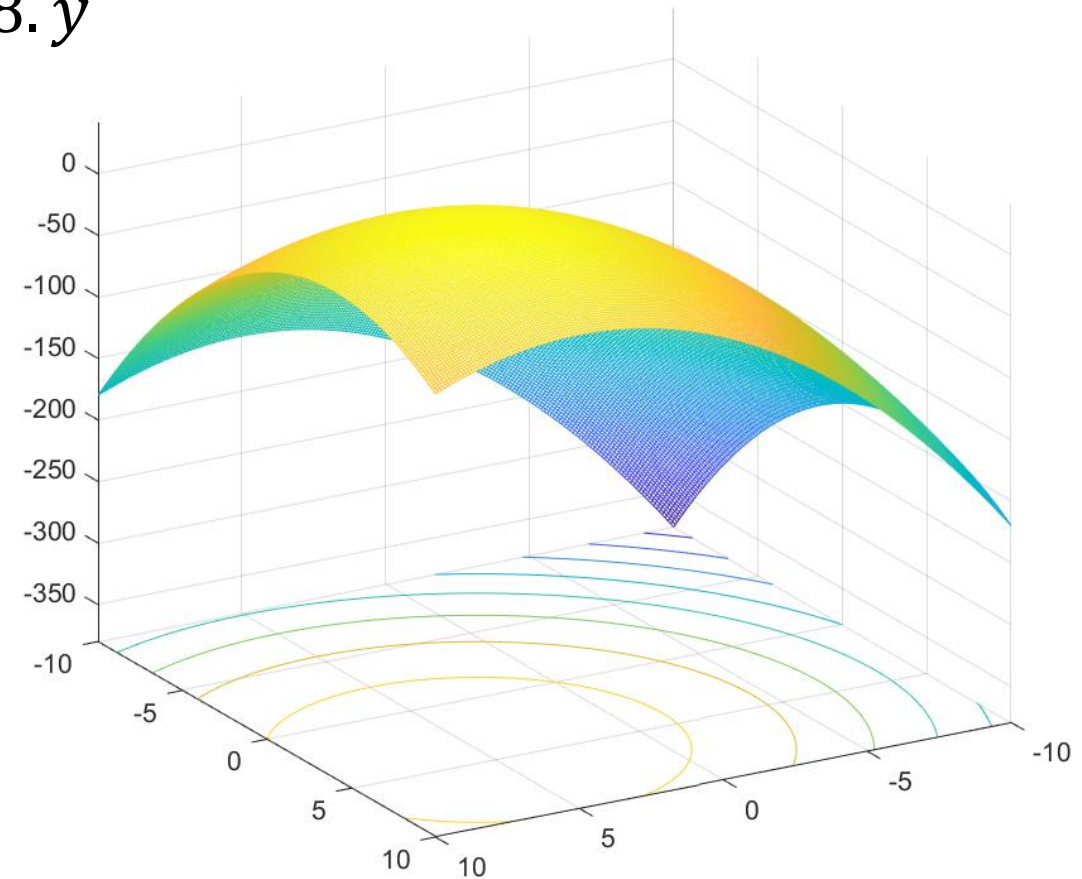
```
f = @(x) -(-x(1).^2+10*x(1)-x(2).^2+8*x(2));
```

```
x0 = [0, 0];
```

```
sol = fminsearch(f, x0);
```

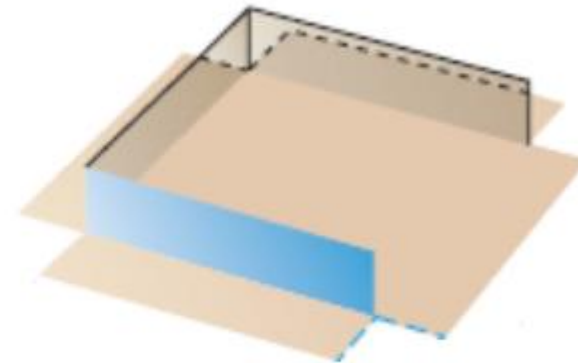
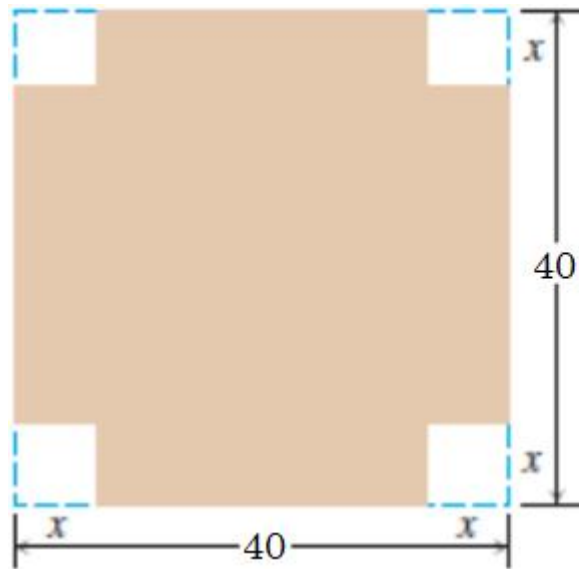
```
disp(sol) % 5, 4
```

```
f(sol) % -41
```



Example 2

- An open rectangular box with square base is made from 40x40cm sheet bended up as shown
- What is the largest possible volume?

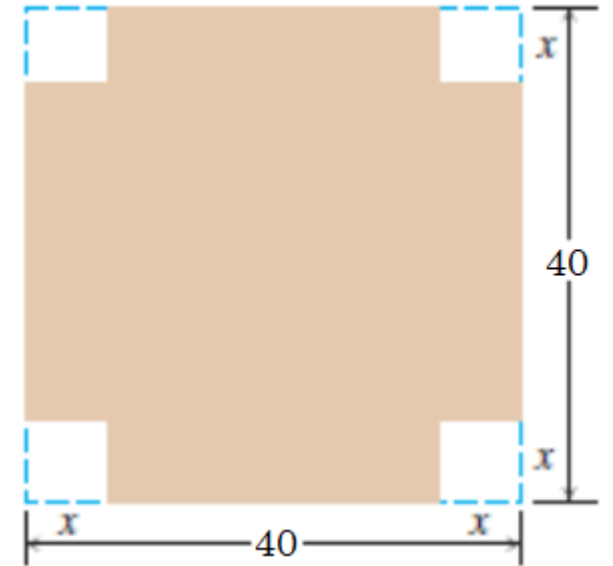


Example 2

- Variable x
- Objective volume:
$$v(x) = x \cdot (40 - 2x)^2 = 1600x - 160x^2 + 4x^3$$
- Subject to constraint:
$$0 < x < 20$$

$$\frac{\delta v(x)}{\delta x} = 1600 - 320x + 12x^2 = 0$$

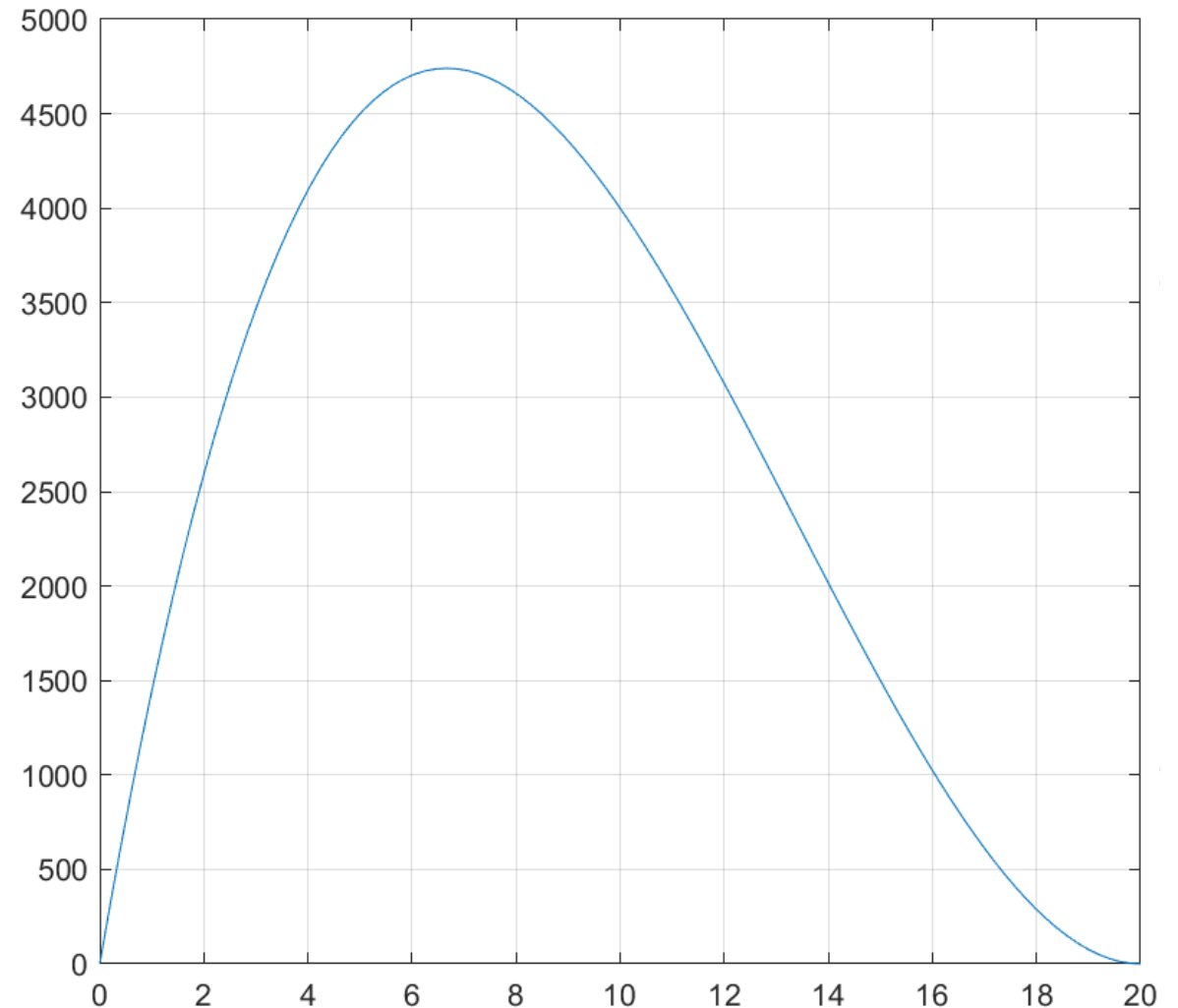
$$133.33 - 26.67x + x^2 = (x - 20) \cdot (x - 6.67) = 0$$



Example 2

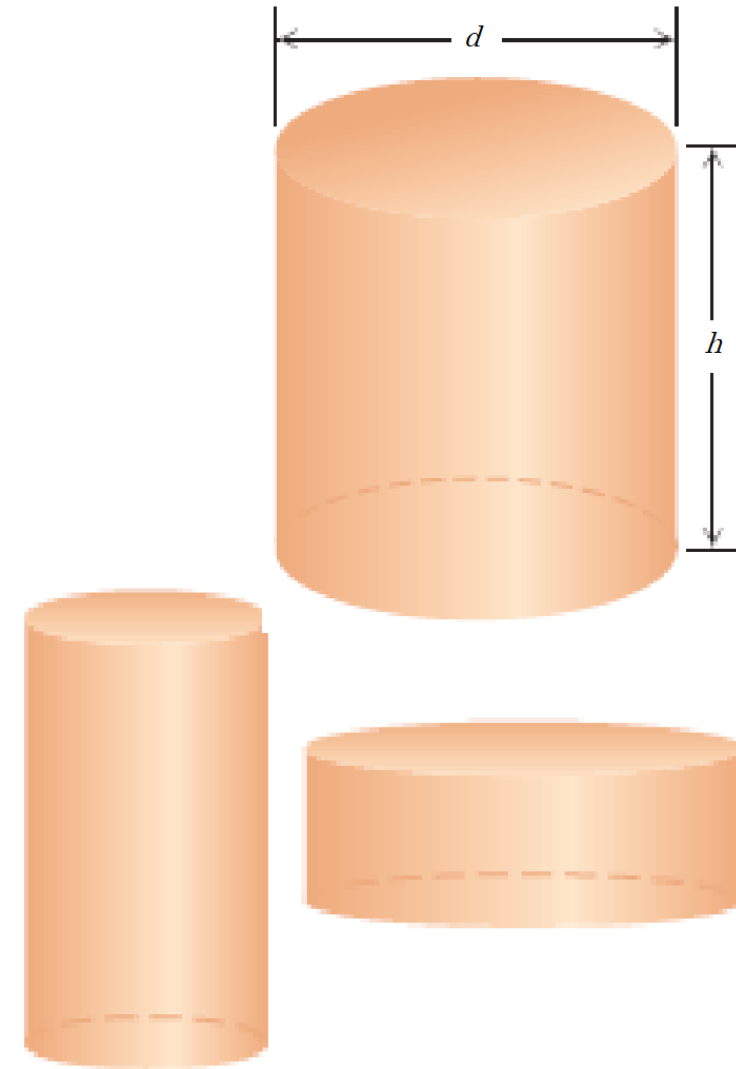
- $v(x) = 1600x - 160x^2 + 4x^3$
- $1600 - 320x + 12x^2 = 0$
 - $x = 20$
 - $x = 6.67$
- Objective volume = 4740.7
- Numerical:

```
x = linspace(0, 20);  
v = 1600.*x-160.*x.^2+4*x.^3;  
plot(x, v), grid  
roots([12 -320 1600])
```



Example 3

- Design optimum cylindrical tank with minimum material and volume 1000 litre
- Variables d and h
- Minimize surface area
- Subject to volume



Example 3

- Variables d, h in metre

- Objective surface:

$$a(d, h) = \pi \cdot d \cdot h + 2 \times 0.25\pi d^2 = \pi d(h + 0.5d)$$

- Subject to constraint:

$$v(d, h) = 0.25\pi d^2 h = 1 \Rightarrow h = \frac{4}{\pi d^2}$$

$$a(d, h) = \pi d \left(\frac{4}{\pi d^2} + 0.5d \right) = \frac{4}{d} + 0.5\pi d^2$$

$$\frac{\delta a(d)}{\delta d} = \pi d - \frac{4}{d^2} = 0 \Rightarrow d = \sqrt[3]{\frac{4}{\pi}} = 1.0839$$

Example 3

- Variables d, h in metre

- Objective surface:

$$a(d, h) = \pi \cdot d \cdot h + 2 \times 0.25\pi d^2 = \pi d(h + 0.5d)$$

- Subject to constraint:

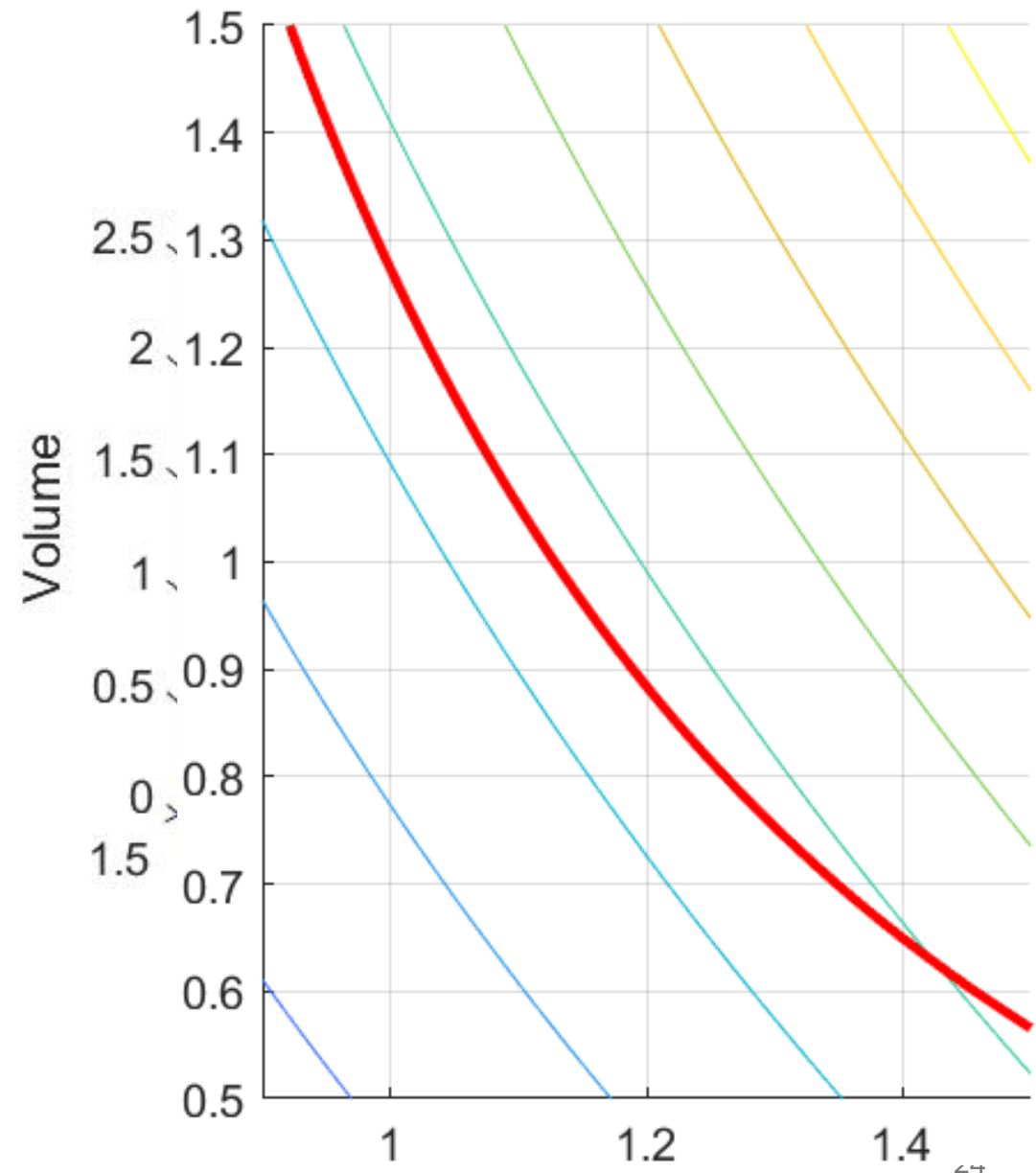
$$v(d, h) = 0.25\pi d^2 h = 1$$

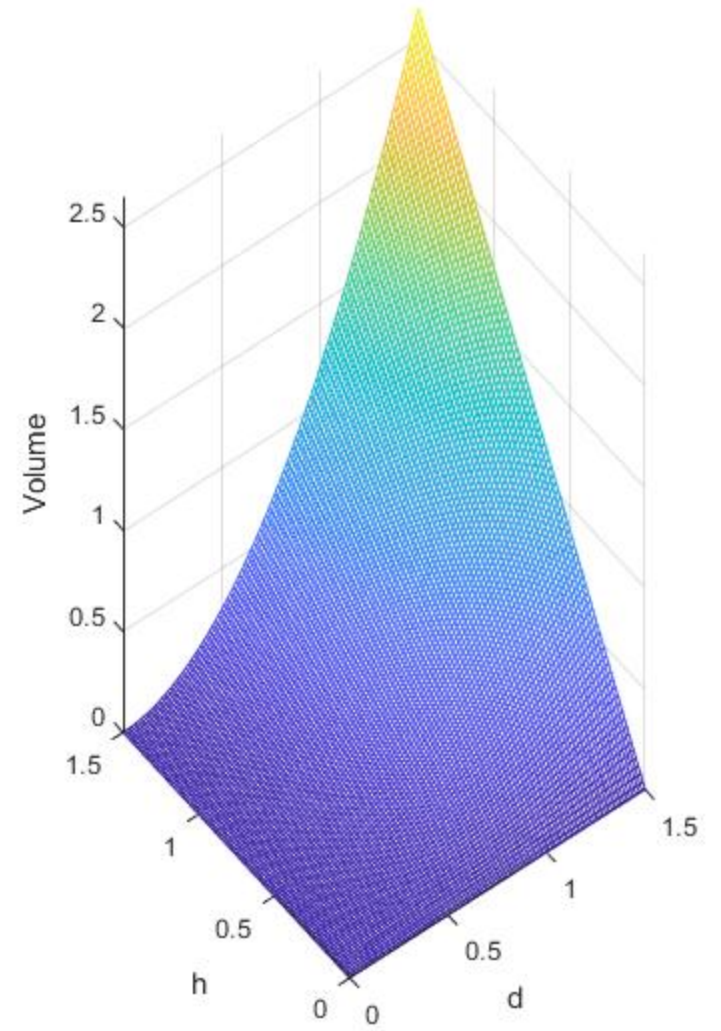
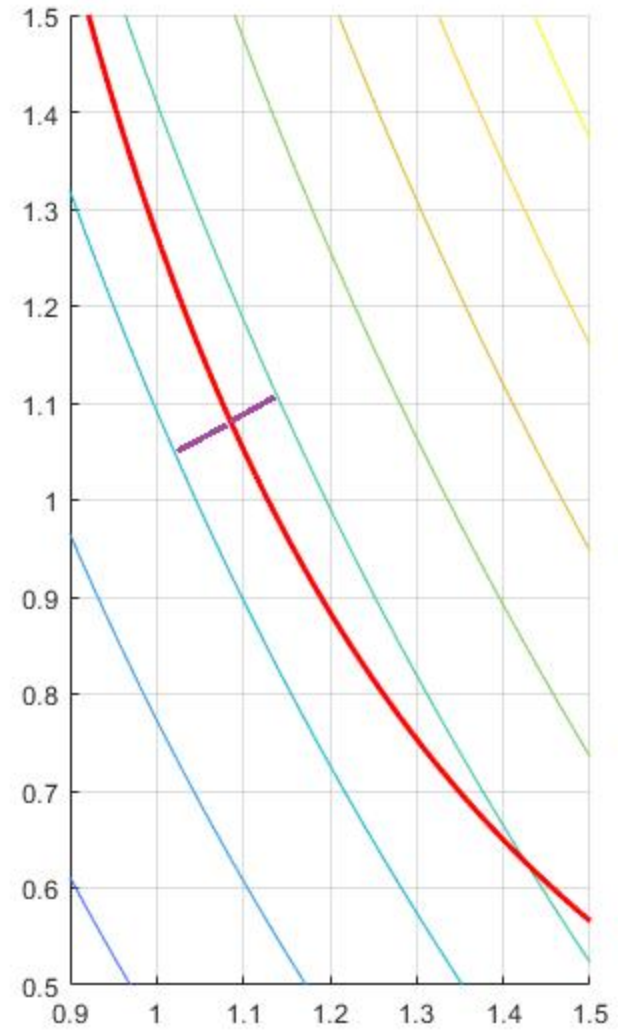
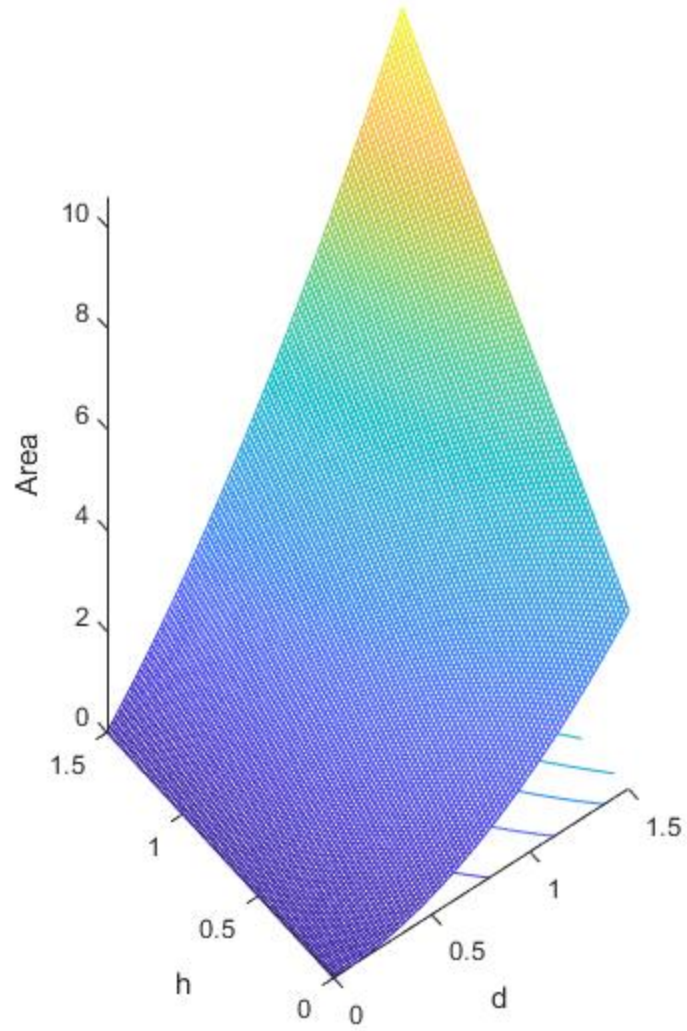
$$d = 1.0839$$

$$h = \frac{4}{\pi d^2} = 1.0839$$

Example 3

```
d1 = linspace(0, 1.5);  
h1 = linspace(0, 1.5);  
[d, h] = meshgrid(d1, h1);  
  
a = pi*d.*(h+0.5*d);  
v = 0.25*pi*d.^2.*h;  
  
meshc(d, h, a)  
meshc(d, h, v)  
  
contour(d, h, v, [1 1], ...  
        LineWidth=2, EdgeColor='red')  
contour(d, h, a)
```





Example 4

- What is the shortest fire truck ladder to get to the building?



Example 4

- Variables x & y
- Objective minimize L :

$$L^2 = y^2 + (x + 4)^2$$

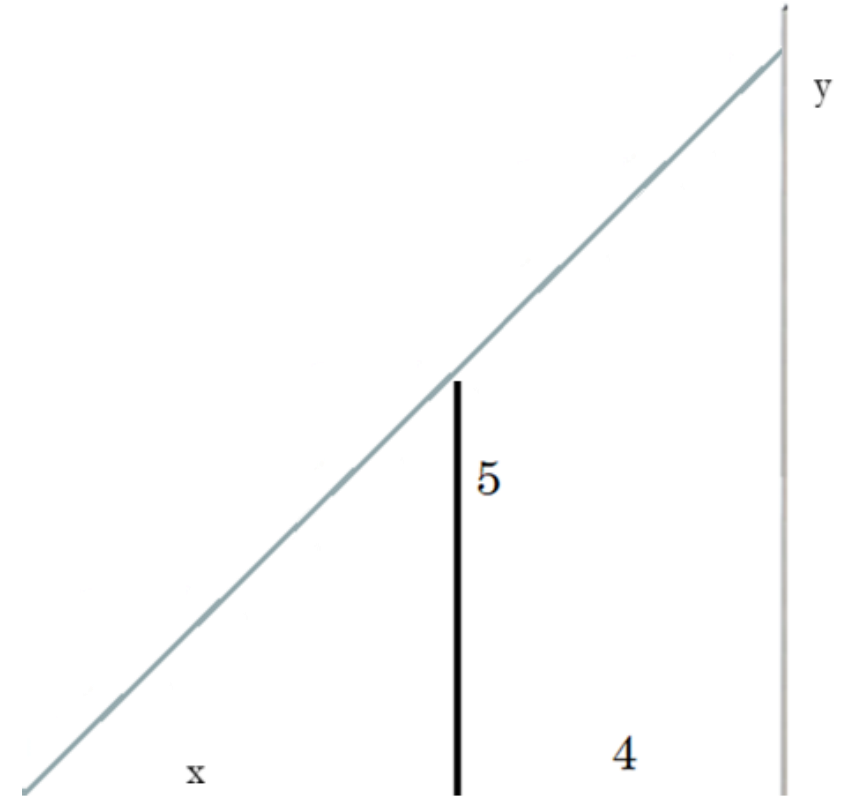
- Constraint:

$$0 < x < \infty$$

$$\tan(\theta) = \frac{y}{4 + x} = \frac{5}{x}$$

$$y = 5(4 + x)/x$$

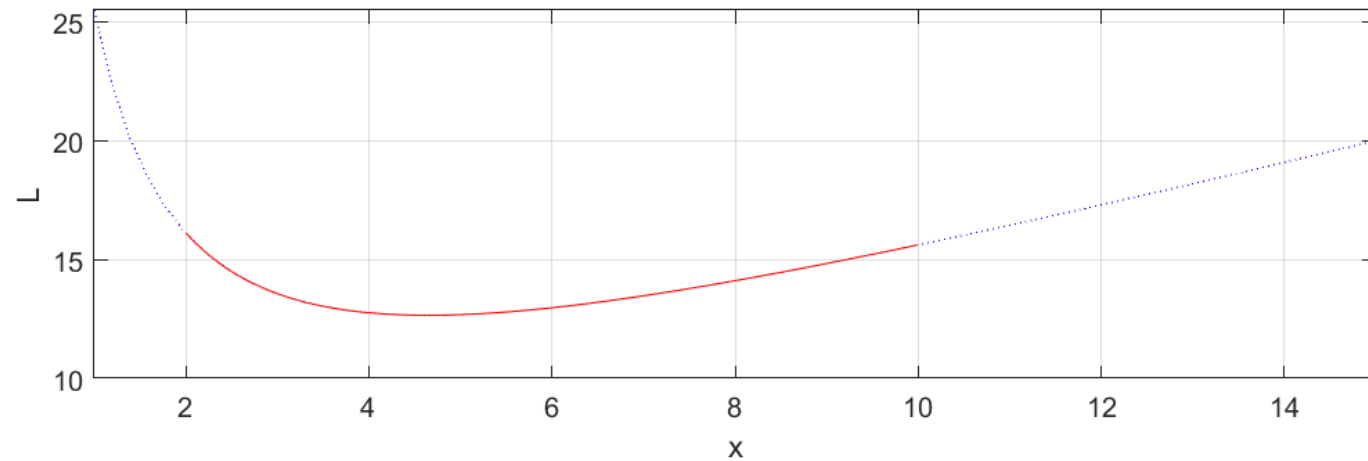
$$L^2 = \left(\frac{5(4 + x)}{x}\right)^2 + (x + 4)^2$$



Example 4

$$L = \sqrt{\left(\frac{5(4+x)}{x}\right)^2 + (x+4)^2}$$

```
h = 5; l = 4;  
x = linspace(1, 15);  
L = sqrt((h*(x+1)./x).^2+(x+1).^2);  
plot(x, L, ':b')  
disp(min(L))    % 12.7017  
  
syms x  
f = sqrt((h*(x+1)./x).^2+(x+1).^2);  
% fplot(f)  
fplot(f, [2 10], 'r')
```



Example 4

```
syms x
f = sqrt((h*(x+1)./x).^2+(x+1).^2);
% fplot(f)
fplot(f, [2 10], 'r')

df = diff(f,x);
fplot(df, [1 15])
```

```
eval(solve(df, x))      % 4.6416, -2.3208 + 4.0197i, -2.3208 - 4.0197i
eval(subs(f, 4.6416))   % 12.7017
```

