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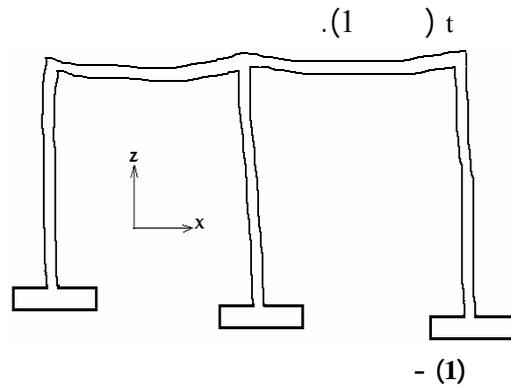
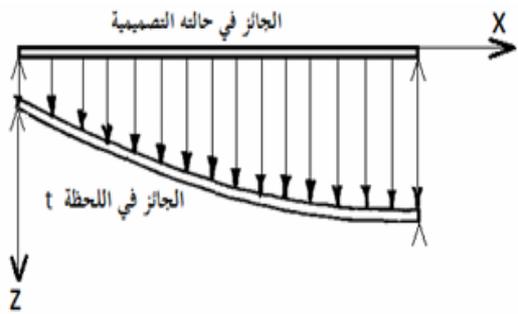
as built

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$$dZ_t = 0.15 X^2 + 0.2 X + 1.32$$

Current Geometrical

:State

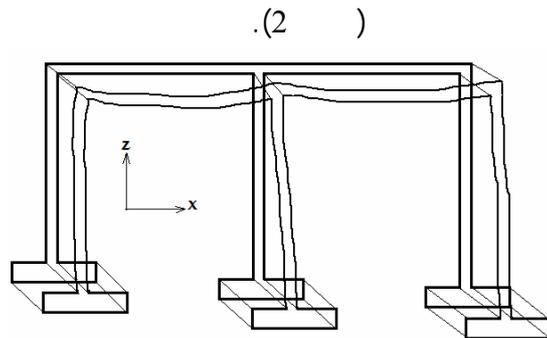


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Geometrical Distortion

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 $Z_t = a.X^2 + b.X + c$

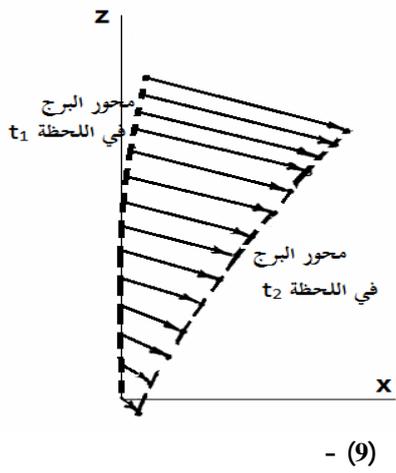


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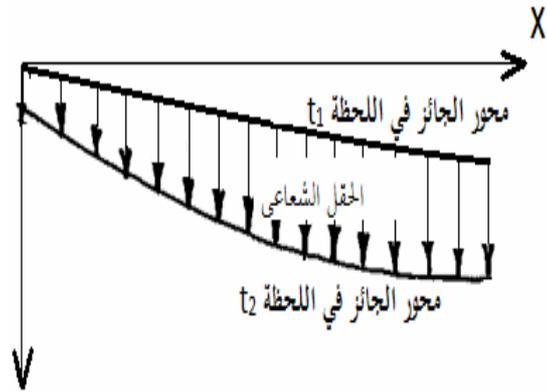
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:Deformation Model

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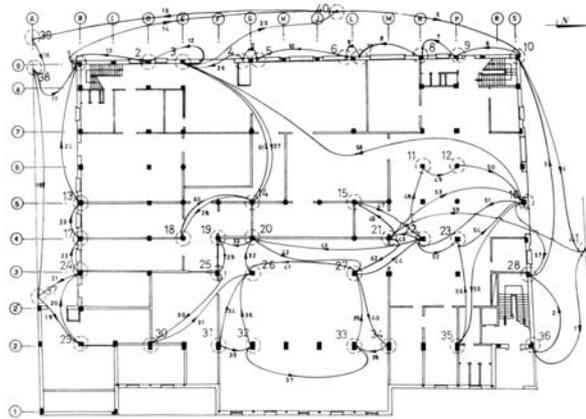
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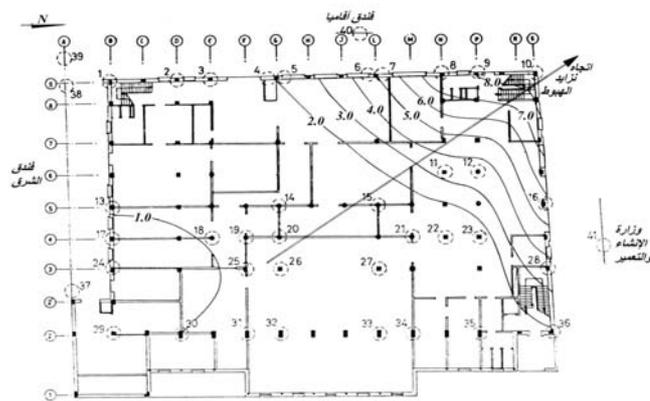
	1 7	2 21	3 17	4 1 21	5 1 17
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	1.8		2.0	7.8	11.6
	1.6		2.2	8.3	12.3
	1.1		2.4	8.9	12.9
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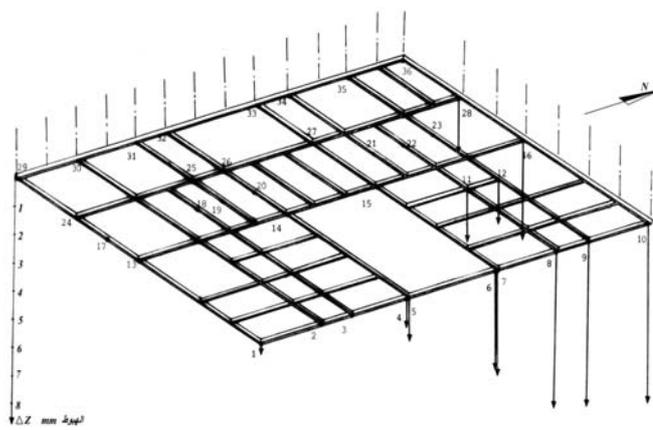
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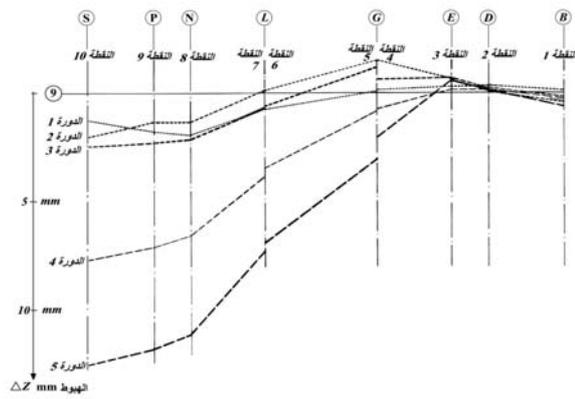
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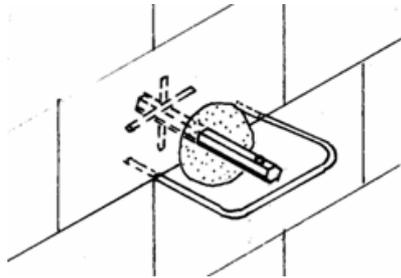
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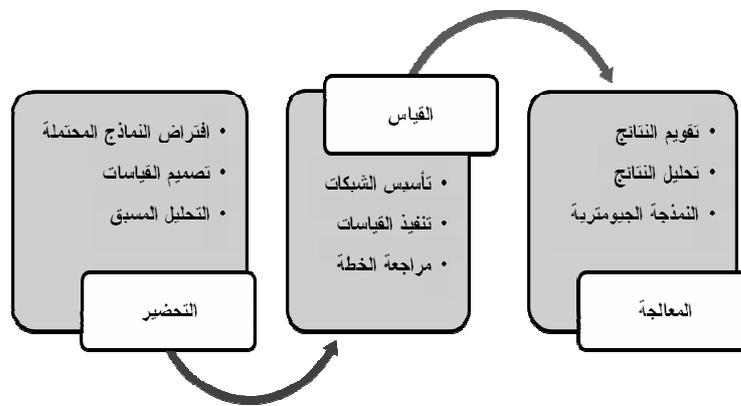
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Deformation Monitoring Processes

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linear interpolation

approximation

Approach
Approximation
Current Geometrical State
Cycle
Deformation
Deterioration
Displacement
Error
Framework
Geodesy
Geomatics
Geometric modeling
Geometrical Distortion
Interpolation
Kinematic
Measurement
Methodology
Metrology
Mistake
Modeling
Monitoring
Reliability
Strain
Surveying
Tolerance

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