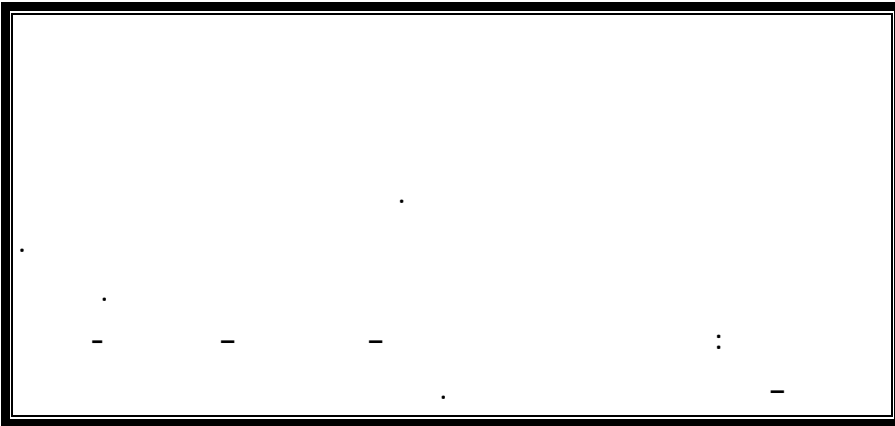


1



: -1

(micro dc motors)

[11] [5] [4] [2] [1]

[7] [3] [2]

commutation)

(current

[7]

[2]

[2]

[3]

[3]

[3]

_____ (rotation speed) _____
(armature current) _____

[3]

(electrical spark) 90%
[8] [7]

- -

[3]

(load current)



: -2

: [7] [1] [5] [4]

. -1

.() -a

. -b

. -c

-2

-3

-4

-5

() -6

-7

-8

.(1)

-9

.U= Ldi/dt :

-10

90%

10%

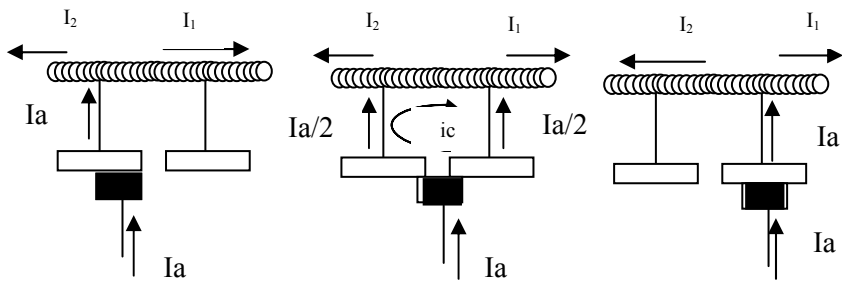
:

-3

[2] [3] .[7]

[2]

:(1)



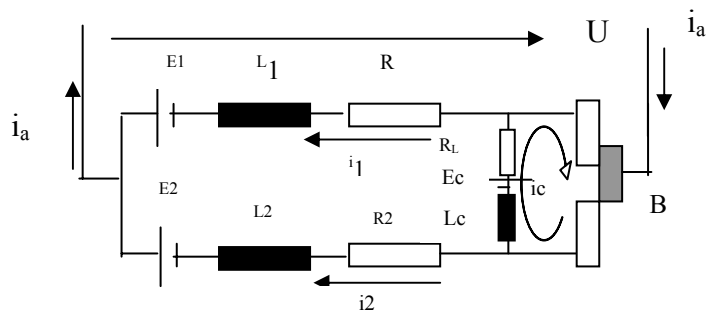
(1)

: [3]

((2) (1))

[2]

: (2)



(2)

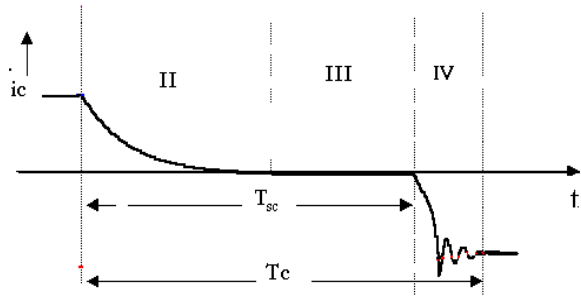
R_c
 $R_2 \quad R_1$
 L_c
 $L_2 \quad L_1$
 $E_c \quad E_2 \quad E_1$

$2 \quad 1 \quad B \quad U$
 $i_a \quad i_c \quad i_2 \quad i_1$

-4

[7] [3] [2]

:



(3)

: T_c :

: T_{sc}

:

I

II

III

IV

V

[7]

:

(II)

[7] [2]

-

$$(III) \quad -$$

$$) \quad ([7]$$

$$(IV) \quad -$$

[3]

:

$$.[\Delta i] :$$

:

$$u_s = l_{rest} \frac{di}{dt}$$

$$di = \Delta i :$$

: dt

:Lrest .[3]

.Lrest [7] [8] dt

)

(

(Us)

10 V :

) [13] [7] [8]

([8] [7]

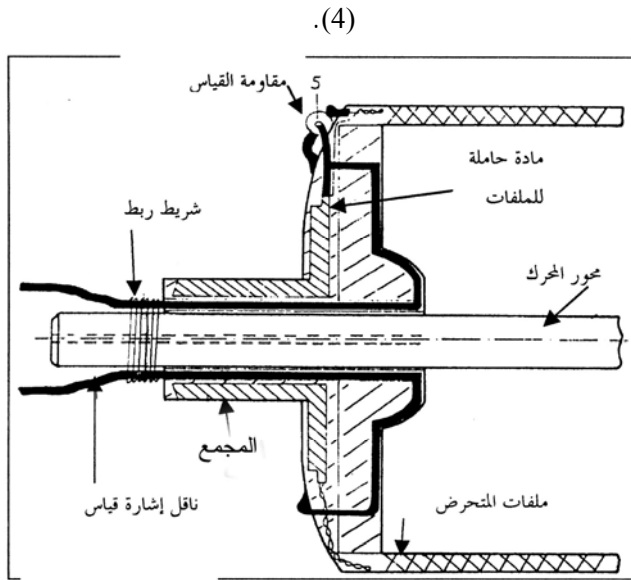
:

$$w = L_{rest} \frac{(\Delta i)^2}{2} \quad [8]$$

)
()

.(
()

. [13] [8] 10 V

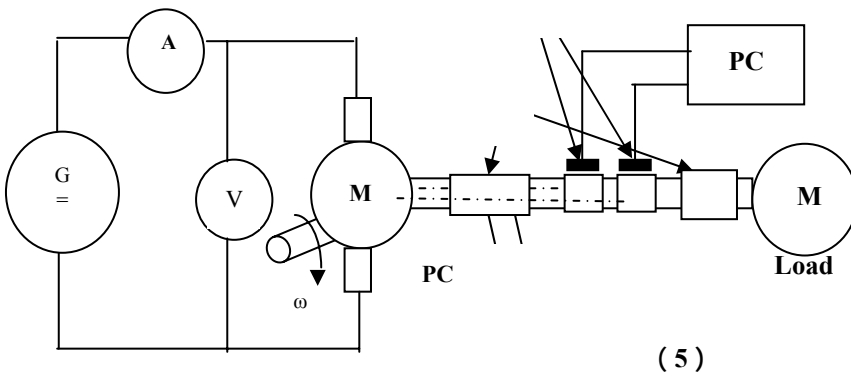


الشكل (4) وصل مقاومة تسلسلية مع إحدى وشائع المتحرض

$i = u/R$:

).

(5)



(5)

(1)

:	:
0.75 A / 12 V	/
5000/3000 min ⁻¹	/
13	
6.5mm / 32 mm	/
1.42 mm) (
0.15 mm) (
0.02 Ω	
5.33 Ω) (
150 μ H) (
1.65 Ω) (
46 μ H) (

[6] [7] [11]

(1)

:

:

5000 min⁻¹, 4500 min⁻¹, 4000 min⁻¹, 3500 min⁻¹, 3000 min⁻¹,
2500 min⁻¹, 2000 min⁻¹, 1500 min⁻¹, 1000 min⁻¹, 500 min⁻¹.

-2

(1)

0.15 A

0.15 A, 0.30 A, 0.45 A, 0.60 A, 0.75 A,
.90 A, 1.05 A, 1.20 A, 1.35 A, 1.50 A.

0

: - 6

: -1-6

: (1)

(500 min⁻¹, 2000 min⁻¹, 35000 min⁻¹, 5000 min⁻¹)

(2) (2)

:

(1)

(2)

(2)

: [3]

$$t_r = \frac{60}{n} \quad [S]$$

) [9]

:(

$$b_B = T_{sc} \times \vartheta_c \quad \vartheta_c = \omega \times r$$

$$\omega = 2 \times n \times \pi / 60 \quad S^{-1}$$

: u_c .

: ω .

: r :

:

)

13

.(

26

60 :

. $60/n$:

. $26 \times n/$

)

.(

(2)

(1)

:

(2)

(1)

(2)

.1

.2

.3

.4

.5

[8] [13]

-

[$U_s = L di/dt$]

.(

[13])



.6

)

([13]

:

:

[13] [8]

U : W= U.I_m.T

:T 10V

I_m

.(2)

(2)

:

- 2-6

(3)

.(0.15 A 0.60 A 1.05 A 1.50 A):

.(4) (3)

:

(5)

()

(2)

(1)

(3)

(4)

(5)



			(6)
			(7)
(3)		(3)	
:	(5)		(4)
			-1
(3)			-2
			-3
			-4

-5

(5)

-6

)

(

(5)

(2)

(1)

:

$$t_{arc} = C \times i_a$$

:

$$t_{arc} = C' \times \Delta i$$

C' C:

:

$$C' = 78.8$$

$$C = 36.6$$

:

L_{rest} :

L_{rest}

-

-

10 V : [8] [13] -

La =150 μ H) La/2 : C/ -7
(1)

() $t_r = \frac{60}{n} = 0.02$ [S] : -8

: [3] :
 $2 \times 13 \times n / 60 = 1300$
2 . 13 . 2X13

() -9
(3))
(5)

Ia =1.5 A 25%)
(Ia = 0.15 A 3%
-10

2X13

. ((5) (4)) .

)
($I_a = 1.5 A$ 7%

($I_a = 0.15 A$ 0.7%)

-11

10% 0.15A :

.1.5 A

10% = 0.15 A :

) 10%

((5) (4) (4) (3)

(10%

:

-12

.((5))

(5) (7) (6)

$W=f(\Delta i^2) \quad W=f(ia^2) :$

[8]

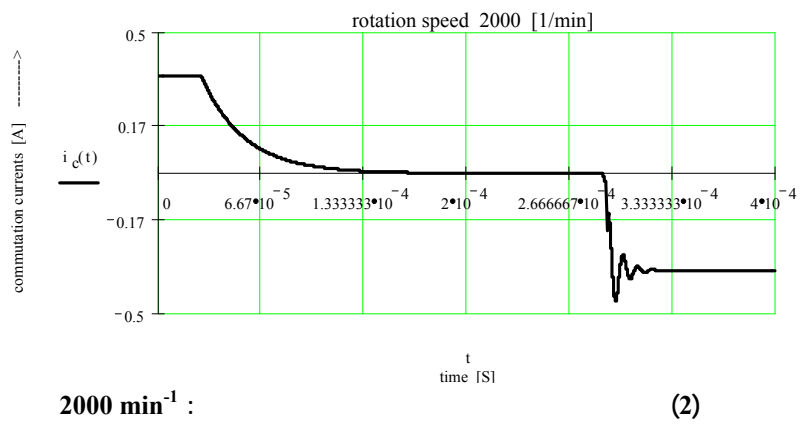
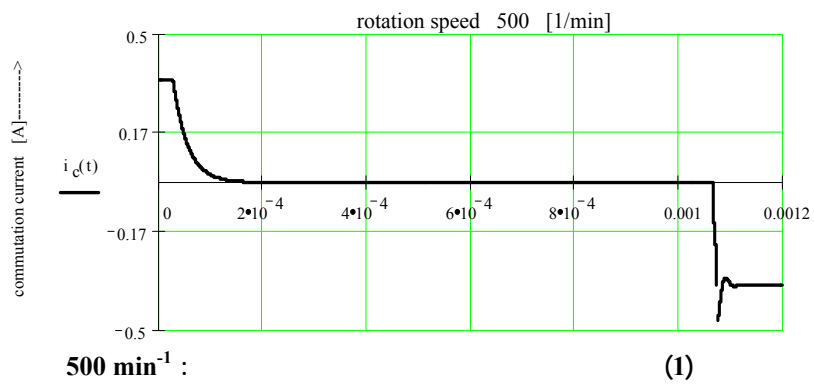
$$w = L_{rest} \frac{(\Delta i)^2}{2} :$$

(5)

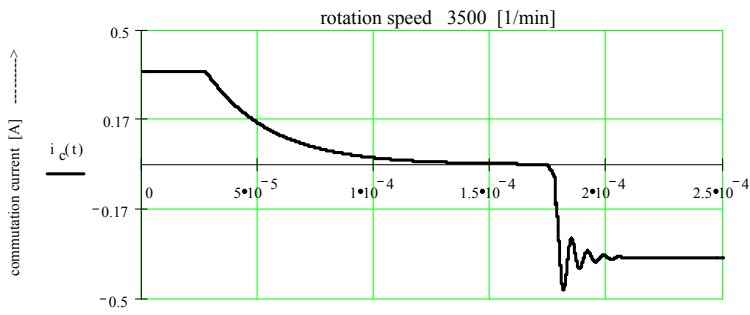
(2)

: -6

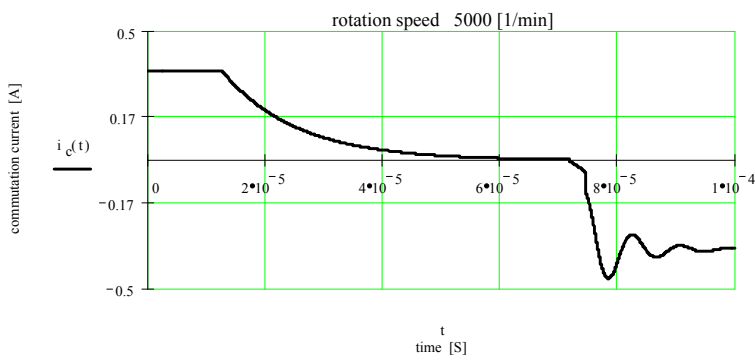
()



(1)



3500 min^{-1} : (3)



5000 min^{-1} : (4)

(1)

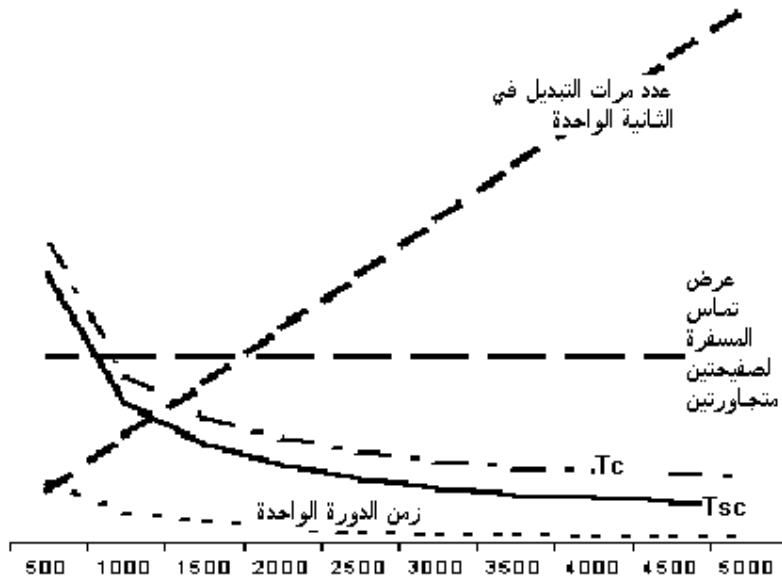
$\times 10^{-6}$		I_a				T_{iv}	T_c	T_{sc}		
[W]	[A]	[A]	ba		[S]	($\times 10^{-6}$ S	($\times 10^{-6}$ S	($\times 10^{-6}$ S	[V]	min^{-1}
69.9	0.466	0.75	0.17527	216.7	0.12	30	1060	1030	5.35	500
69.9	0.466	0.75	0.17528	433.3	0.06	30	545	515	6.70	1000
69.9	0.466	0.75	0.17611	650.0	0.04	30	375	345	8.05	1500
69.9	0.466	0.75	0.17621	866.7	0.03	30	290	260	9.40	2000
69.9	0.466	0.75	0.17498	1083.3	0.024	30	235	205	10.75	2500
69.9	0.466	0.75	0.17561	1300.0	0.02	30	200	170	12.00	3000
69.9	0.466	0.75	0.17510	1520.5	0.0171	30	177	147	13.40	3500
69.9	0.466	0.75	0.17489	1733.3	0.015	30	158	128	14.80	4000
69.9	0.466	0.75	0.17498	1954.9	0.0133	30	144	114	16.15	4500
69.9	0.466	0.75	0.17527	2166.6	0.012	30	133	103	17.50	5000

:(2)

: ()

()

(2)



:(1)

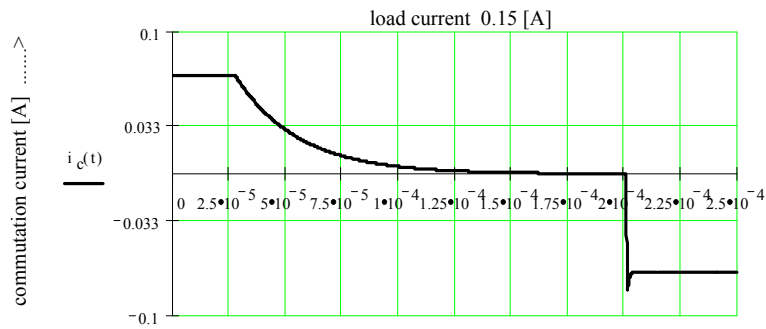
)

(

.(2)

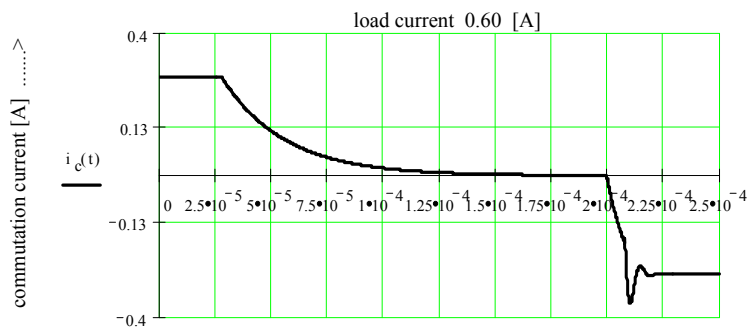
).

(2)



0.15 A

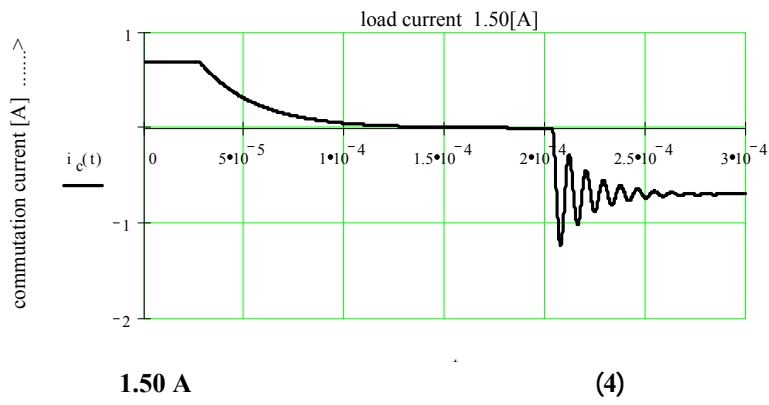
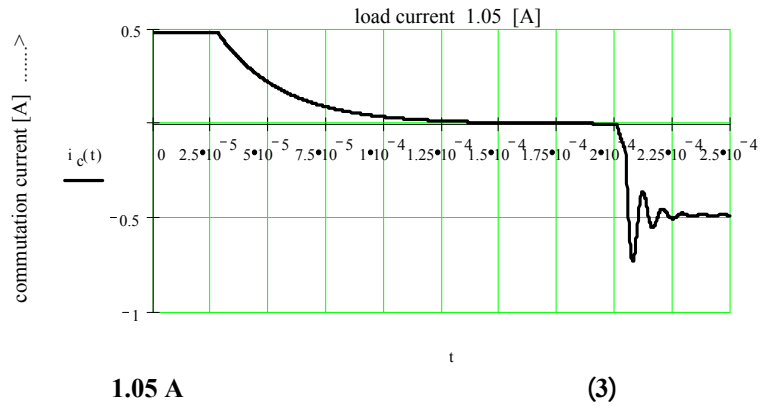
(1)



0.60 A

(2)

(3)



(3)

X10 ⁻⁶ [W]	[A]			X10 ⁻⁶ S	[S]	[A]	T _{IV}	T _c	T _{sc}	[V]	[A]
							X10 ⁻⁶ [S]				
2.0500	0.082	0.0065	0.0283	130	0.02	0.069	5	175	170	8.80	0.15
8.6500	0.173	0.0130	0.0556	260	0.02	0.138	10	180	170	9.60	0.30
20.325	0.271	0.0195	0.0810	390	0.02	0.207	15	185	170	10.4	0.45
42.130	0.383	0.0286	0.1146	572	0.02	0.277	22	192	170	11.2	0.60
69.900	0.466	0.0390	0.1500	780	0.02	0.346	30	200	170	12.0	0.75
113.75	0.650	0.0455	0.1707	910	0.02	0.415	35	205	170	12.8	0.90
154.00	0.770	0.0520	0.1905	1040	0.02	0.484	40	210	170	13.6	1.05
201.37	0.895	0.0585	0.2093	1170	0.02	0.554	45	215	170	14.4	1.20
267.50	1.070	0.0650	0.2273	1300	0.02	0.623	50	220	170	15.2	1.35
338.25	1.230	0.0715	0.2444	1430	0.02	0.692	55	225	170	16.0	1.50

:(3)

:

)

.(

)

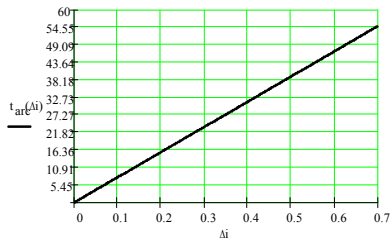
(

)

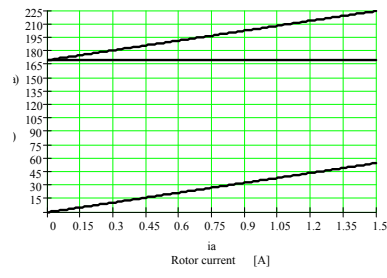
(

:

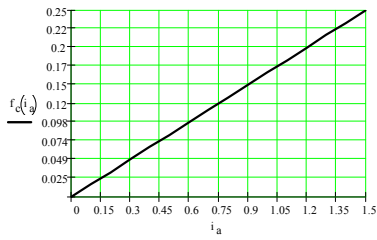
(4)



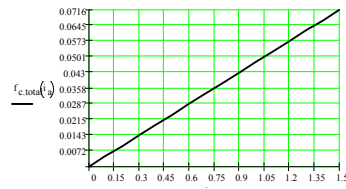
(1)



(2)



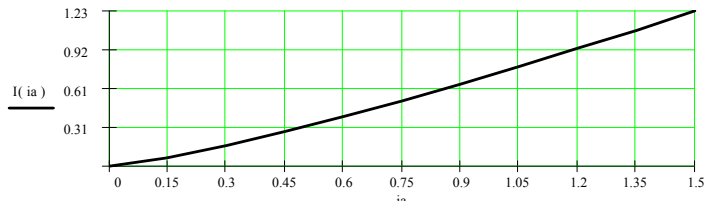
(3)



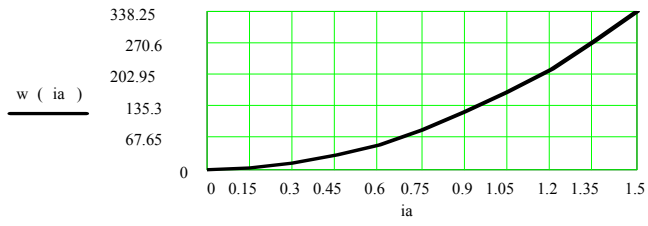
(4)

()

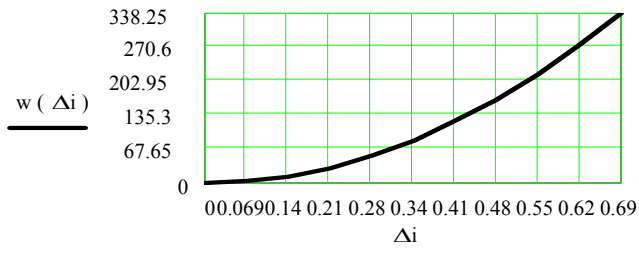
(5)



() (5)



(6)



(7)

(5)

:

. : . -[1]

- -

.1995

. - [2]

.2003 -18 -

. -[3]

.2005 -21 -

[4]- H. Fujita Recent Progress of microactuators and micromotors
Microsystem Technologies Springer Berlin / Heidelberg June 2005

[5]- Junge and Mueller Electro- engineering lexicon Weinheim, New York
Basel, Cambridge, Tokyo 2001

[6]- E. Jucker Physical behavior of DC- Micro motors free ferrate rotor
Porte cap la Chaux- de- Fonds Switzerland 2001

[7]- Wahbi, Said Untersuchung zur Erhöhung des Kommutator
Bürstenapparates von GMM Dissertation TU Dresden 1989

[8]- Paulig, Eberhard Anforderung an Gleitkontakte in GMM
Anforderung an Gleitkontakte in GMM Dissertation TU Dresden 1985

[9]- Schneidetr, G Untersuchung an Kleinstmaschinen Dissertation TU
Berlin 1996

[10]- Conntantinescu- Simon, Liviu Elektrische Energietechnik Vieweg
& Sohn Verlag Braunschweig/ Wiesbaden 2001

[11]- Herta GmbH Projkterungsvorschrift für GMM Herta,
Germany199 , 2000, 2002

[12]- Müller, G Elektrische Maschinen Verlag Technik Berlin 1997

[13] – Bätz, Rutzen Elektrotechnische SchaltgeräteVerlag Technik
Berlin 1998

.2007/6/26 :