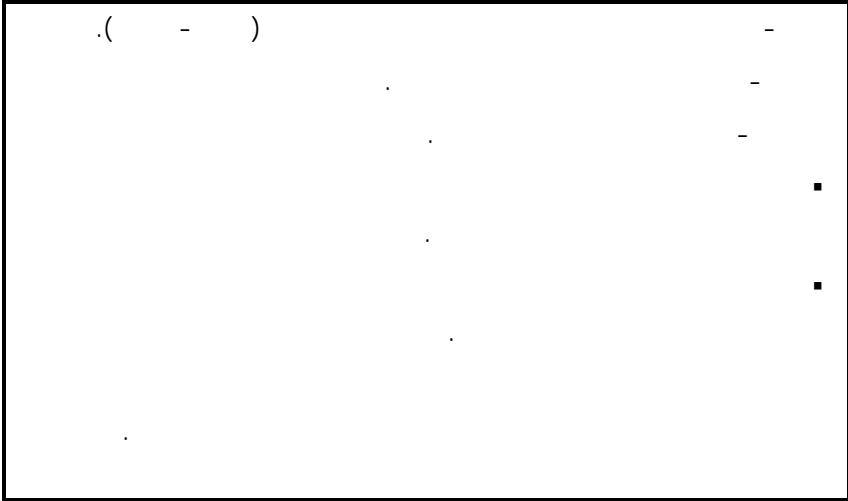


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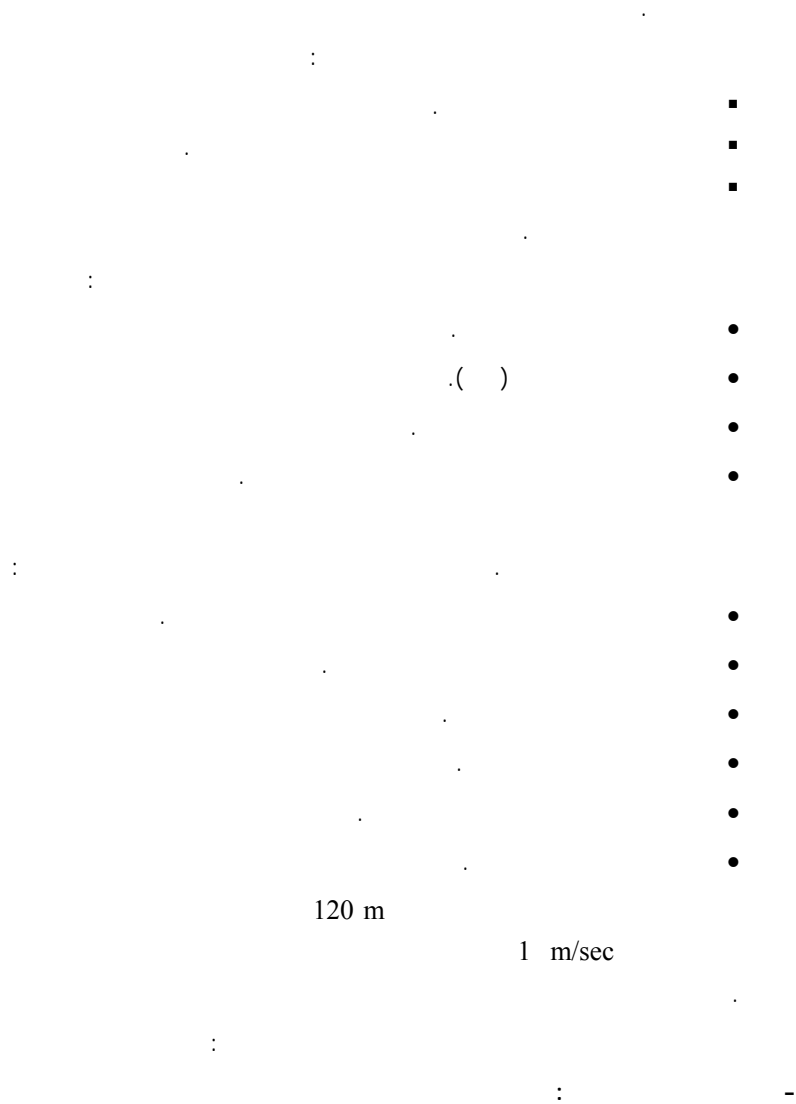


**:Introduction -1**

(... - - )

:

- 
-





: -

: -

)

f = 150[HZ]

(

f = 50 [HZ]

22[Kw]

150[HZ] 380[V]

f=50[HZ] 380[V]

**:Mathematical Model -2**

**: -1-2**

:

$$\Delta P_H = \delta_H \cdot \frac{f}{100} \left( \frac{B}{10000} \right)^2 \quad (1)$$

:

$$\Delta P_W = \delta_W \cdot \left( \Delta \frac{f}{100} \cdot \frac{B}{10000} \right)^2 \quad (2)$$

$$. f=150[\text{HZ}]$$

$$f=150[\text{HZ}]$$

$$: f=50[\text{HZ}]$$

$$\Delta P_{Fe50} \approx \Delta P_{Fe150}$$

$$B_{p50} < B_{p150} \quad (3)$$

$$B_{Z50} < B_{Z150}$$

$$(2,3\text{w/kg}) (1,6\text{w/kg})$$

$$.50[\text{HZ}]$$

$$(2.6\text{w/kg})$$

:

$$\Delta P_{Fe} = \Delta P_H + \Delta P_W \quad (4)$$

:

**-2-2**

$$f=150[\text{HZ}]$$

:

$$\Delta P_{Fe50} = 2,6 \cdot B_{Z1}^2 \cdot G_{Z1} \quad (5)$$

150[HZ]

2,6

. f=50[HZ]

:

$$\Delta P_{fe150} = \Delta P_{Fe} \cdot B_{Z1}^2 \cdot G_{Z1} \quad (6)$$

: (3)

$$2,6 \cdot B_{Z1}^2 = \Delta P_{Fe} \cdot B_{Z1}^2$$

$$\frac{B'_{Z1}}{B_{Z1}} = \sqrt{\frac{2,6}{\Delta P_{Fe}}} \quad (7)$$

:

$$\frac{B'_{P150}}{B_{P50}} = \sqrt{\frac{2,6}{\Delta P_{Fe}}} \quad (8)$$

:

:

(8)

$$B'_{P150} = B_{P50} \sqrt{\frac{2,6}{\Delta P_{Fe}}} \quad (9)$$

.(9)

:

**-3-2**

:

**-1-3-2**

:

q<sub>1</sub>

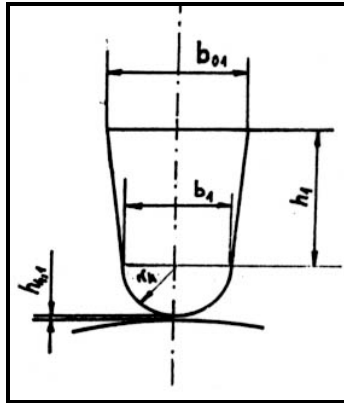
$\bar{Z}_2, \bar{Z}_1$

$$q_1 = \frac{\bar{Z}_1}{2P \cdot m_1} \quad (10)$$

: -2-3-2

(2)  $(G_{iZ}, r_4, h_{4,1}, b_1, h_1, b_{01})$

$$S_{z_{1net}} = \frac{(b_{01} - 2G_{iZ}) + (b_1 - 2G_{iZ})}{2} (h_1 - G_{iZ}) + \frac{\pi(r_4 - 2G_{iZ})^2}{2} \quad (11)$$



(2)

: -3-3-2

DNX

Z

:

$$Z_1 = Z \cdot q_1 \quad (12)$$

: -4-3-2

(2)  $(h_{r1}, D_Z)$

:

---


$$D = D_Z - 2 (h_{r1} + h_1 + r_4 + h_{4,1}) \quad (13)$$

$$\tau = \frac{\pi \cdot D}{2P} \quad (14)$$

$$\phi = \frac{K_E \cdot U_f}{4 \cdot K_B \cdot f \cdot K_u \cdot Z_1} \quad (15)$$

$$K_u = K_S \cdot K_g \approx 0,958 \quad :K_u$$

$$K_S = 1 \quad :K_S$$

$$K_g = 0,958 \quad :K_g$$

$$K_B = 1,103 \quad :K_B$$

$$K_E = 0,96 \quad :K_E$$

$$L = \frac{\phi}{B_p \cdot \alpha_i \cdot \tau} \quad (16)$$

$$\alpha_i = 0,66 \quad : \alpha_i$$

$$L_w = L + 5 \quad (17)$$

$$\delta = 0,15 + (0,02 \div 0,025) \sqrt{D \cdot L} \quad (18)$$



: -6-3-2

$$D_w = (0.3 \div 0.35) D_5 \quad (19)$$

: -4-2

: -1-4-2

: (3)

$$t_1 = \frac{\pi \cdot D}{Z_1} \quad (20)$$

: ■

$$t_{Z_1} = \frac{\pi \cdot D_2}{Z_1} \quad (21)$$

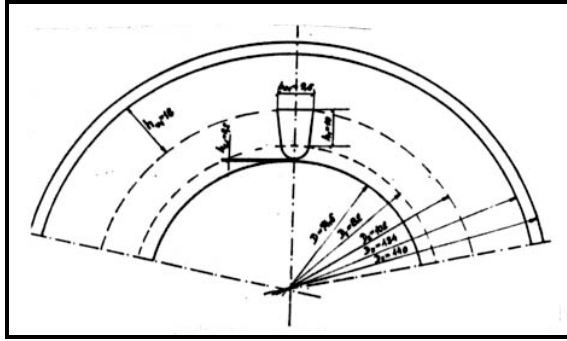
: ■

$$t_{Z_1} = \frac{\pi \cdot D_1}{Z_1} \quad (22)$$

:

$$b_{Z_1} = t_{Z_1} - b_{01}$$

$$b_{Z_2} = t_{Z_2} - b_1 \quad (23)$$



(3)

: . . -2-4-2

$$E_{Pr} = \frac{K_E \cdot U_f}{2 \cdot K_u \cdot Z_1} \quad (24)$$

:

$$P_i = P + \Delta P_{cu2} + \Delta P_m \quad (25)$$

1,5%

:

$\Delta P_m$

$$\Delta P_m = \Delta P_w + 0,01 P_n \quad (26)$$

:

$\Delta P_w$

$:0,01 P_n$

: -3-4-2

$$\eta_w = \frac{P}{P_i} \quad (27)$$

: -4-4-2

$$I_2 = \frac{P \cdot 10^3}{m_2 E_{Pr} \cdot \eta_w} \quad (28)$$

$$R_2 = \frac{P_{cu2}}{m \cdot I_2^2} \quad (29)$$

$$I_{Pr} = \frac{I_2}{P} \quad (30)$$

$$I_{Pn'} = \frac{I_{Pr}}{\beta} \quad (31)$$

: :β

$$\beta = 2 \sin \frac{\pi}{Z_2} \quad (32)$$

: -5-4-2

$$J_{Pr} = \frac{I_2 \cdot R_2}{(1 + \alpha \cdot \Delta\theta) L_{Pr} \lambda + \frac{2(1 + \alpha \cdot \Delta\theta) \cdot \pi \cdot D_{P'e_n}}{1,3 \cdot \beta \cdot \lambda \cdot Z_2}} \quad (33)$$

:

: L<sub>Pr</sub>

: D<sub>P'n</sub>

$$D_{P'n} = D_{W_2} - h_{P'n} \quad (34)$$

$$J_{P'_n} = \frac{I_{P'_n}}{S_{P'_n}} \quad (35)$$

-  $S_{P'_n}$  :

$$S_{Pr} = \frac{I_{Pr}}{J_{Pr}} \quad (36)$$

$$D_{Pr} = 2\sqrt{\frac{S_{Pr}}{\pi}} \quad (37)$$

$S_{Pr}$

$$J_{Pr} = \frac{I_{Pr}}{S_{Pr}} \quad (38)$$

-6-4-2

: 0.7mm

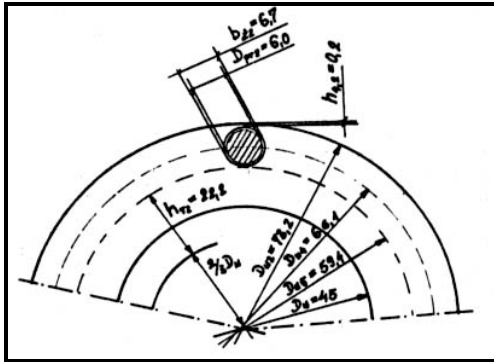
$$b_{Z_2} = D_{Pr} + 0.7 \quad (39)$$

(4)

$$h_{t_2} = \frac{D_{W_5} - D_W}{2} + \frac{D_W}{3} \quad (40)$$

$$t_2 = \frac{\pi \cdot D_{W_4}}{Z_2} \quad (41)$$

$$b_{Z_{0,5}} = t_2 - b_{Z_2} \quad (42)$$



(4)

$$:$$

-7-4-2

$$:$$

-1-7-4-2

$$B_{Z_1} = \frac{B_p \cdot t_1}{0,93 \cdot b_{Z_1}} \quad (43)$$

$$B_{Z_2} = \frac{B_p \cdot t_1}{0,93 \cdot b_{Z_2}}$$

:

$$B_{Z_{sr}} = \frac{B_{Z_1} + B_{Z_2}}{2} \quad (44)$$

$$:$$

-2-7-4-2

$$B_{r1} = \frac{\phi}{0,93 \cdot 2 \cdot L \cdot h_{r2}} \quad (45)$$

: -3-7-4-2

$$B_{Z2} = \frac{B_P \cdot t_2}{0,93 \cdot b_{Z_{0,5}}} \quad (46)$$

: -4-7-4-2

$$B_{r2} = \frac{\phi}{0,93 \cdot 2 \cdot h_{r2} \cdot L_w} \quad (47)$$

$H_{r2}, H_{z2}, H_{r1},$

$B_{r2}, B_{z2}, B_{r1}, B_{z \bar{s}r}$  Hz  $\bar{s}r$

: -8-4-2

:

: -1-8-4-2

$$U_{mp} = 1,6 \cdot K_c \cdot B_P \cdot \delta \quad (48)$$

: -2-8-4-2

$$U_{m_{z1}} = 2 \cdot h_{z1} \cdot H_{z \bar{s}r} \quad (49)$$

: -3-8-4-2

$$U_{mr1} = L_{r1} \cdot H_{r1} \cdot K_{r1} \quad (50)$$

$$K_{r1} = 0,45 \quad :K_r :$$

:  $L_{r1}$

$$L_{r1} = \frac{\pi \cdot D_z}{2P} \quad (51)$$

: -4-8-4-2

$$U_{mr2} = L_{r2} \cdot H_{r2} \cdot K_{r2} \quad (52)$$

$$K_r = 0,6 \quad :K_{r2} :$$

:  $L_{r2}$

$$L_{r2} = \frac{\pi \cdot (D_w - 2h_{z2})}{2P} \quad (53)$$

:

-5-8-4-2

$$U_{mZ2} = 2h_{z2} \cdot H_{Z2} \quad (54)$$

:

-9-4-2

$$\Sigma F_m = U_{mP} + U_{mZ1} + U_{mr1} + U_{mZ2} + U_{mr2} \quad (55)$$

:

$$I_\mu = \frac{\Sigma F_m}{2.7 \cdot K_u \cdot Z_1} \quad (56)$$

:

$$I_{\mu\%} = \frac{I_\mu}{I_n} \cdot 100 \quad (57)$$

:

$$K_{nZ} = \frac{U_{mP} + U_{mZ1} + U_{mZ2}}{U_{mP}} \quad (58)$$

:

-9-4-2

$$L_{cz} = 1,4 \cdot \tau + 4 \text{ cm} \quad (59)$$

$$L_{ZW} = 2 (L_{cz} + L) \quad (60)$$

$$\Delta\theta = 40 \text{ c}$$

$$\theta_z = 15 \text{ c}$$

:

-1-9-4-2

$$R_{155} = 1,16 \frac{L_w}{\lambda \cdot S_{pr}} \quad (61)$$

:

-2-9-4-2

$$R_{Pr55} = 1,16 \frac{L_w}{\lambda \cdot S_{Pr2}} \quad (62)$$

:

-3-9-4-2

$$R_{P'n55} = 1,16 \frac{t_2}{\lambda \cdot S_{P'n}} \quad (63)$$

:

$$R_{255} = R_{Pr55} + \frac{2R_{P'n55}}{\beta^2} \quad (64)$$

:

-4-9-4-2

$$R'_2 = R_{ed} \cdot R_{255} \quad (65)$$

:R<sub>ed</sub> :

$$R_{ed} = \frac{12(K_u \cdot Z_1)^2}{Z_2} \quad (66)$$

:

-10-4-2

:

-1-10-4-2

$$G_{cul} = 3 Z_1 \cdot L_{Zw} \cdot S_{cu} \cdot \gamma \quad (67)$$

- \gamma :

:

-2-10-4-2

$$G_{Pr} = Z_2 \cdot L_w \cdot S_{Pr2} \cdot \gamma \quad (68)$$

:

-3-10-4-2

$$G_{P'n} = 2\pi D_{W2} \cdot S_{P'n2} \cdot \gamma \quad (69)$$

:

-4-10-4-2

$$G_{r1} = \frac{\pi(D_z^2 - D_2^2)}{4} K_{Fe} \cdot L \cdot \gamma \quad (70)$$

:





---

1kw

$$G_{kw} = \frac{G}{P_n} \quad (80)$$

: -11-4-2

: -1-11-4-2

$$\Delta P_{cu1} = 3 \cdot I_1^2 \cdot R_{155} \quad (81)$$

: -2-11-4-2

$$\Delta P_{cu2} = Z_2 \cdot I_{Pr}^2 \cdot R_{Pr55} \quad (82)$$

: -3-11-4-2

$$\Delta P_{r1} = \Delta P_{Fe150} \cdot K_j \cdot \frac{(B_{r1})^2}{10000} G_{r1} \quad (83)$$

: -4-11-4-2

$$\Delta P_{Z1} = \Delta P_{Fe150} \cdot K_Z \cdot \frac{(B_{Z1})^2}{10000} G_{Z1} \quad (84)$$

$K_Z = 2$   $K_Z :$

: -5-11-4-2

: (26)

$$\Delta P = \Delta P_{cu1} + \Delta P_{cu2} + \Delta P_{r1} + \Delta P_{Z1} + \Delta P_m \quad (85)$$

:

$$\eta = \frac{P}{P + \Delta P} \quad (86)$$

: -12-4-2

$$\Delta P_0 = 3 \cdot I_\mu^2 \cdot R_{l_{55}} \quad (87)$$

:

$$\Delta P_{St} = \Delta P_0 + \Delta P_{r1} + \Delta P_{Z1} + \Delta P_m \quad (88)$$

$$I_{ow} = \frac{\Delta P_{st}}{3U_f} \quad (89)$$

:

$$I_0 = \sqrt{I_\mu^2 + I_{ow}^2} \quad (90)$$

$$\cos \varphi_0 = \frac{I_{ow}}{I_0} \quad (91)$$

:

$$S\% = \frac{\Delta P_{cu2}}{P + \Delta P_m + \Delta P_{cu2}} \% \quad (92)$$

:

$$n = n_s (1-S) \quad (93)$$

: -13-4-2

: -1-13-4-2

$$\lambda_{Z1} = 1,256 \left( K_{h4} + \frac{h_1}{3b_1} K_{tr} \right) \quad (94)$$

:

$$\frac{b_1}{b_{01}} : \frac{h_{u,1}}{b_1}, \frac{I_{Pr1}}{b_1} : K_{h4}$$

$$: K_{tr}$$

$$-2-13-4-2$$

$$\lambda_{c1} = 1,256 \frac{q_1}{L} K_{c2} K_s \cdot L_{c2} \quad (95)$$

$$K_{c2} = 0,2 \quad 500 [v] : K_{c2}$$

$$-3-13-4-2$$

$$\lambda_{h1} = 1,256 \cdot 0,304 \frac{\tau}{\delta \cdot K_c \cdot K_{nz}} q_1 \cdot \delta_h \quad (96)$$

$$\delta_h = 8,2 \cdot 10^{-3} \quad \delta_h :$$

$$\lambda_1 = \lambda_{z1} + \lambda_{c1} + \lambda_{h1} \quad (97)$$

$$\lambda_2 = \lambda_{z2} + \lambda_{c2} + \lambda_{h2} \quad (98)$$

$$\lambda_{z2} = 0,66 + 1,256 K_{h4} \quad (99)$$

$$\frac{P_{Pr}}{b}, \frac{h_{4,2}}{b} : K_{h4} :$$

$$: \lambda_{c2}$$

$$\lambda_{c2} = 0,46 \log \frac{1,5D_{p'n}}{2(L_{p'n} + h_{p'n})} \quad (100)$$

:

: $\lambda_{h2}$

$$\lambda_{h2} = 1,256 \frac{t_2}{11,9K_c \cdot \delta} \quad (101)$$

:

**-14-4-2**

:

**-1-14-4-2**

$$X_1 = 0,1256 \cdot \frac{f_1}{100} \left( \frac{Z_1}{100} \right)^2 \cdot \frac{L}{P \cdot q_1} \lambda_1 \quad (102)$$

:

**-2-14-4-2**

$$X'_2 = 0,251 \frac{f_1}{100} \cdot \frac{m_1}{Z_2} \left( \frac{Z_1 \cdot \text{kg}}{100} \right)^2 \cdot L_w \cdot \lambda_2 \quad (103)$$

:

**-15-4-2**

:

$$Z_{zw} = \sqrt{R_{zw}^2 + X_{zw}^2} \quad (104)$$

:

: $R_{zw}$  :

$$R_{zw} = R_{155} + (1 + \tau_1) R_{255} \quad (105)$$

:

: $\tau_1$  :

$$\tau_1 = \frac{I_\mu \cdot X_1}{U_f - I_\mu \cdot X_1} \quad (106)$$

:

: $X_{zw}$

$$X_{zw} = X_1 + (1 + \tau_1) X_{255} \quad (107)$$

---


$$I_{zw} = \frac{U_f}{Z_{zw}} \quad (108)$$

$$v_I = \frac{I_{zw}}{I_1} \quad (109)$$

$$\cos \varphi_{zw} = \frac{R_{zw}}{Z_{zw}} \quad (110)$$

$$P_{\max} = \frac{3 \cdot U_f \cdot (I_{zw} - I_0)}{2(1 + \cos \varphi_{zw})} \quad (111)$$

$$v_P = \frac{P_{\max}}{P} \quad (112)$$

$$M_{zn} = \frac{P_n}{n_s} \cdot 9,8 \quad (113)$$

$$M_{roz} = \frac{3U_f^2}{R_{zw}^2 + X_{zw}^2} \cdot R_2 \cdot \frac{0,975}{n_s} \cdot 9,8 \quad (114)$$

$$v_M = \frac{M_{\max}}{M_{zw}} \quad (115)$$

: -3-16-4-2

$$S_k = \frac{R'_2}{X_1 + X'_2} \quad (116)$$

: -4-16-4-2

$$M_{\max} = \frac{m_1 \cdot U_f^2}{\sigma_1} \cdot \frac{1}{2[R_1 + \sqrt{R_1^2 + (X_1 + \sigma_1 X'_2)^2}} \cdot \frac{0,975}{n_s} \cdot 9,8 \quad (117)$$

:  $\sigma_1$  :

$$\sigma_1 = 1 + \tau_1 \quad (118)$$

$$v'_M = \frac{M_{\max}}{M_{zn}} \quad (119)$$

(119 , 115 ,

$$(R'_2 , R_1 , \varphi_{zw} , \varphi_0 , I_{zw} , I_0) \quad (M_{zn} , P_{\max} , I_{1f} , \varphi_n) \quad (112)$$

: -5-2

$$2.5\% \quad (25)$$

$$(1)$$

: -6-2

---

50 [HZ]

[HZ]

(10)  
. (1)

:

**-7-2**

$h_{4,1} = h_{4,2} = 0.2 \text{ mm}$

(13-4-2)

. (15-4-2)

(94)

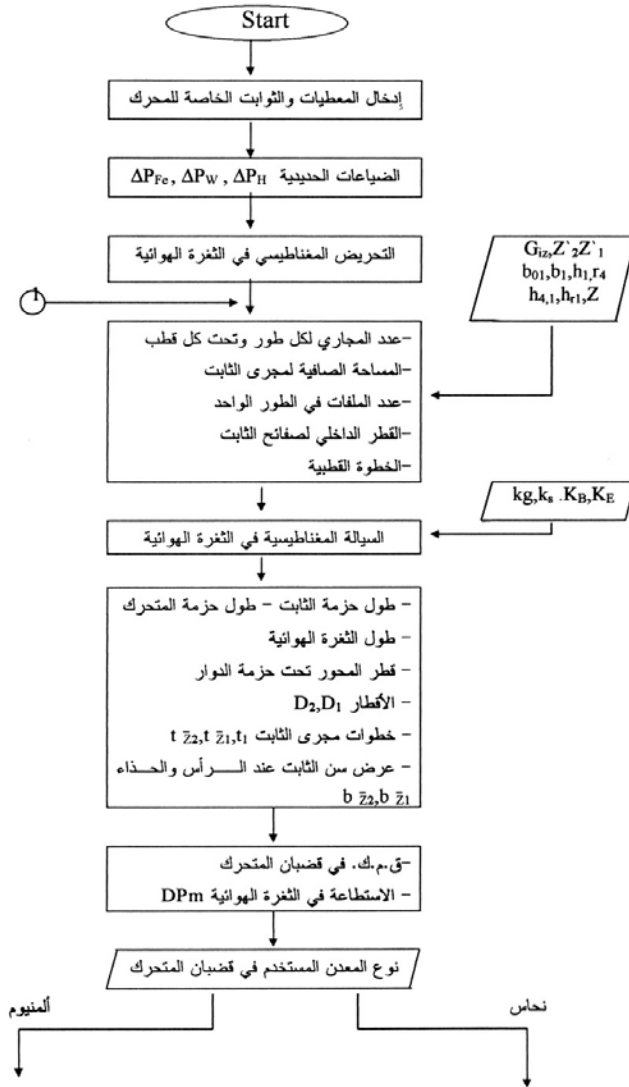
$h_{4,1} = h_{4,2}$

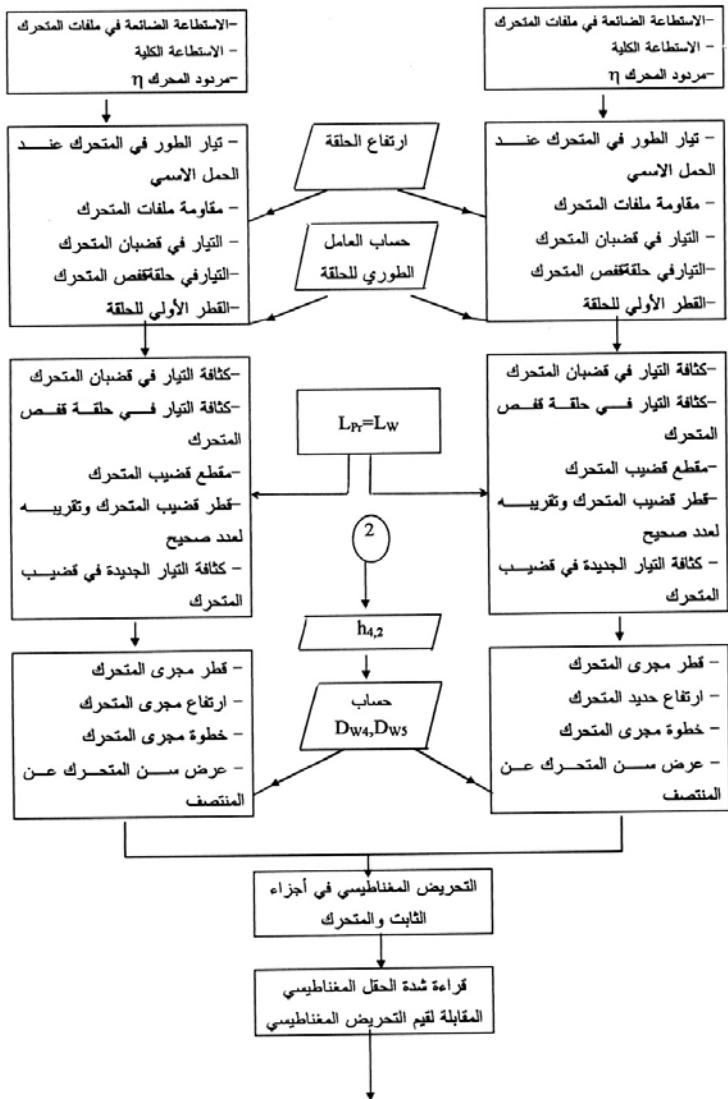
. (1)

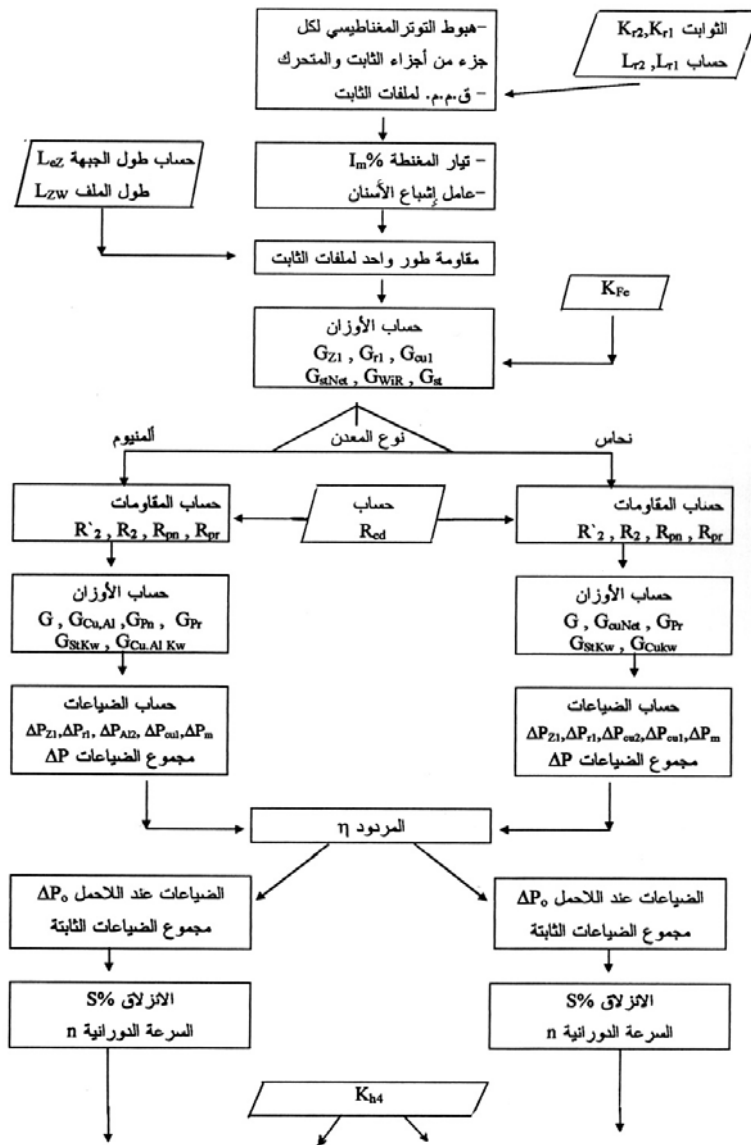


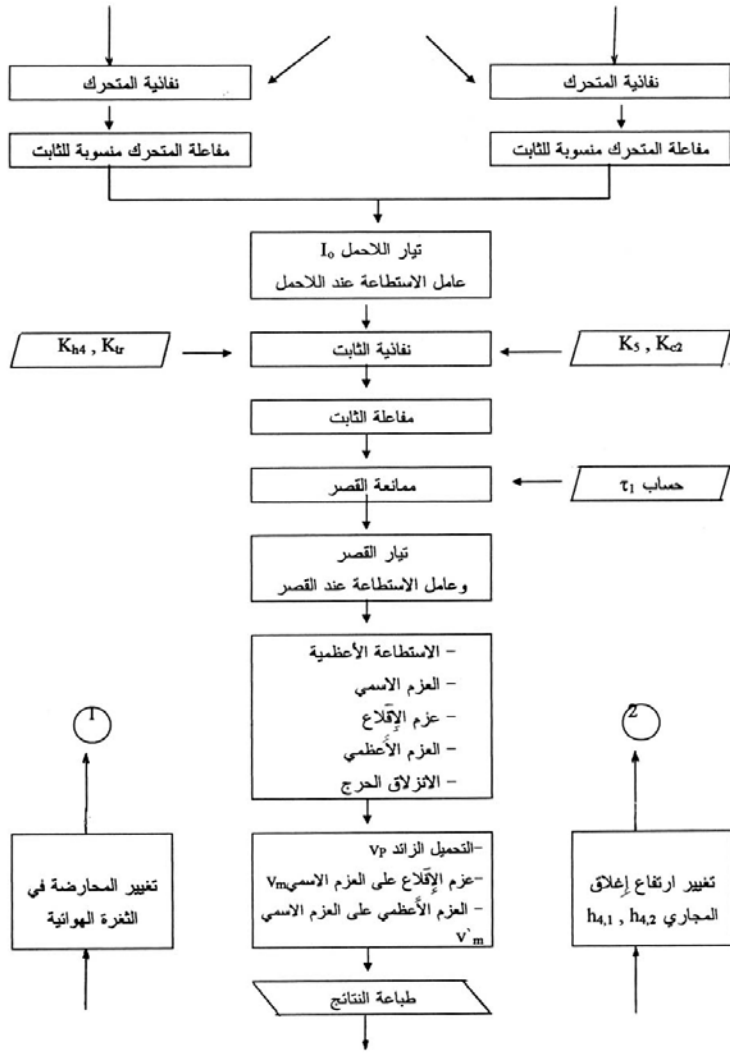
## :Algorithm

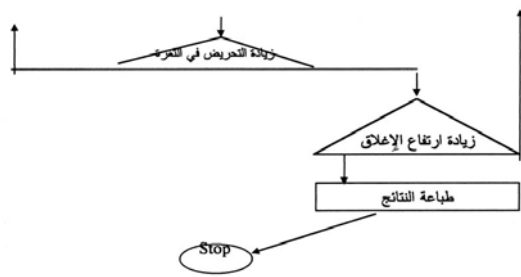
-3











(1)

**:Numerical Example****-4**

380[v]

22kw

f=150[HZ]

:

f=50 [HZ]

1	P	Kw	22
2	U	v	380
3	$I_{lf}$	A	49.5
4	$\cos \varphi$	-	0.82
5	$\eta$	-	0.82
6	$D_z$	mm	170
7	D	mm	90
8	$D_{w2}$	mm	87.6
9	$D_w$	mm	60
10	n	r.p.m	285°
11	L	mm	700
12	$\bar{Z}_1$	-	24

13	$\bar{Z}_2$	-	18
14	$q_1$	-	4
15	$Z_{1f}$	-	28
16	$\delta$	mm	1.2
17	$\alpha_i$	-	0.68
18	$K_C$	-	1
19	$K_{nz}$	-	1.03
20		-	2,6-0,5w/kg

TP7

:                   ▪  
 .0.482 [Ts]  
 :                   ▪  
 . 0.482 [T]  
 :                   ▪  
 .0.52 [T]  
 :                   ▪  
 0.52 [Ts]  
 :                   ▪  
 . 0.5 mm

		1	2	3	4	5	
$B_p$	Ts	0.482	0.482	0.52	0.52	0.52	0.532
$L_{Fe}$	Mm	550	550	505	505	505	700
$D_Z$	Mm	134	134	134	134	134	170
$D_{W2}$	Mm	73.2	73.2	73.2	73.2	73.2	87.6

Convec.	-	$\Delta$	$\Delta$	$\lambda$	$\lambda$	$\lambda$	$\lambda$
Z <sub>lf</sub>	-	28	28	16	16	16	28
R155	$\Omega$	0.273	0.273	0.0944	0.0944	0.0944	0.22
Red	-	480	480	156	156	156	480
R <sub>2</sub>	$\Omega$	0.212	0.3206	0.089	0.136	0.089	0.185
R <sub>ZW</sub>	$\Omega$	0.39	0.602	0.185	0.234	0.185	0.414
h <sub>4,1</sub> =h <sub>4,2</sub>	Mm	0.2	0.2	0.2	0.2	0.5	0.7
X <sub>1</sub>	$\Omega$	1.115	1.115	0.340	0.340	0.467	0.62
X <sub>2</sub>	$\Omega$	1.37	1.38	0.448	0.424	0.560	0.65
X <sub>ZW</sub>	$\Omega$	2.222	2.532	0.800	0.776	1.043	1.3
Z <sub>ZW</sub>	$\Omega$	2.26	2.60	0.821	0.809	0.821	1.36
I <sub>μ</sub> %	%	31.5	31.5	36.2	36.2	36.2	28.4
S	-	0.012	0.01947	0.1575	0.0261	0.1575	0.042
n <sub>zn</sub>	r.p.m	8890	8820	8860	8780	8860	2850
S <sub>K</sub>	-	0.0853	0.1284	0.1128	0.1780	0.0866	0.1445
η	-	0.834	0.827	0.828	0.822	0.828	0.848
D <sub>pr2</sub>	Mm	6.0	6.0	5.0	5.0	5.0	7.0
G <sub>cu N</sub>	Kg	6.44	4.51	4.97	3.68	4.97	9.84
G <sub>stN</sub>	Kg	36.67	36.67	34.41	34.41	34.41	62.36
G	Kg	43.11	41.18	39.38	38.09	39.38	72.0
G <sub>cu KW</sub>	kg/kw	0.292	0.205	0.226	0.167	0.226	0.447
G <sub>KW</sub>	kg/kw	1.96	1.87	1.79	1.68	1.79	3.28
M <sub>zn</sub>	N.m	23.98	23.98	23.98	23.98	23.98	23.98
M <sub>roz</sub>	N.m	19.16	21.40	20.23	31.86	12.20	-
M <sub>max</sub>	N.m	80.3	79.60	91.66	92.39	72.10	-
M <sub>max</sub> /M <sub>zn</sub>	-	3.35	3.32	3.82	3.85	3.00	1.94
M <sub>roz</sub> /M <sub>zn</sub>	-	0.8	0.894	0.844	1.320	0.531	0.66
P <sub>max</sub> /P <sub>n</sub>	-	3.49	2.71	3.04	2.94	2.41	-

### :Results Analysis And Conclusion

-5

Bp=0.482

21.4%

550

700

[Ts]

0.52[Ts]

27.9%

505

---

.36.2%    0.52[T]  
 -  
 550 mm  
 40.4%  
 43%  
 45.6%    505mm  
 . 47.4%  
 . 1.3M<sub>zn</sub>    -  
 f=50[HZ]  
 h<sub>4.1</sub> = h<sub>4.2</sub> = 0.7mm  
 .M<sub>roz</sub> = 0.66 M<sub>zn</sub>  
 f=150 [HZ]  
 0.53 M<sub>zn</sub>    h<sub>4.1</sub> = h<sub>4.2</sub> = 0.5 mm  
 0.7mm    150 [HZ]  
 0.5 M<sub>zn</sub>  
 0.3 < h<sub>4.1</sub> = h<sub>4.2</sub> < 0.4  
 .0.5M<sub>zn</sub> < M<sub>roz</sub> < 0.8M<sub>zn</sub>  
 h<sub>4.1</sub> = h<sub>4.2</sub> = 0.2  
 .M<sub>roz</sub> = 0.8 M<sub>zn</sub>  
 h<sub>4.1</sub>    1.3 M<sub>zn</sub>  
 = h<sub>4.2</sub> ≤ 0.2 mm



$$f=150[\text{HZ}]$$

$$h_{4,1} = h_{4,2} =$$

$$: \quad 0.2\text{mm}$$

$$n_{zn} = 8780 \text{ r.p.m.}, \eta = 0.822, S_{zn} = 0.0261, M_{roz} = 1.3 M_{zn}$$

:

$$v_m = 3.86$$

$$Bp = 0.482 [\text{Ts}]$$

$$Bp = 0.52$$

$$v_m = 3.27$$

$$0.482 [\text{Ts}]$$

$$v_m = 3.32$$

$$v_m = 3.85$$

$$0.52 [\text{Ts}]$$

$$f = 50[\text{HZ}]$$

$$.v_m = 1.94$$

$$0.5 \text{ mm}$$

$$\Delta P_{Fe50} = 1.6 \text{ w/kg}$$

$$44.1 \%$$

$$\eta = 0.82$$

$$0.02 \div 0.06$$

$$S_{zn} \leq 0.03$$

$$8780 \div 8870$$



	$S_{zn} \leq 0.03$	:	
		:	
f=150[HZ]			-1
		:	
	$M_{roZ} \geq 1.3 M_{zn}$		-2
		:	
$h_{4,1} = h_{4,2} \leq 0.2 \text{ mm}$		▪	
		▪	
		:	
	f=150[HZ]		-3
47.4 %			
	$n_{zn} = 8780 \text{ r.p.m}$		-4
		:	
	f = 50[HZ]		

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.			$\delta_H$
.			$\delta_w$
.	$B_{Z1}$	.	$\Delta$
.	$B_p$	.	$G_{Z1}$
.	$G_{iz}$	.	$m_1$
.	$D_Z$	.	$Z$
	$U_f$		$D_s$
	$D_{w2}$		$m_2$
	$\Delta\theta$		$\alpha$
	$k_c$		$\lambda$
	$h_{22}$		$h_{Z1}$
			$k_r$
	$n_s$	.	$n_{zn}$
.	$\lambda_{h1}$	.	$Kc_Z$
		.	$\lambda_{h2}$

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## Computer Aided Comparing Deep-Well Induction Motors

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### Abstract

The deep-well pumps are practically and widely used to pump water up from wells. These pumps are driven by squirrel-cage induction motors where the pump is directly connected with the induction motor it drives.

They form a pump-motor set or a deep-well set.

Economioally, the cost of digging a well proportionates with the diameter of the hole opening.

This diameter is related to the deep-well set dimensions. Whenever the dimensions of the deep-well set are small, the cost of digging a hole will be notably less.

From here, in this research we shall test the possibility of designing a deep-well induction motor with a voltage of  $f=150$  Hz frequency in a small size. and in trifold speed of the induction motor which has same power and functions as the motor with a voltage of  $f=50$  Hz frequency and where the essential parameters of the motor aren't worse than the motor with  $f=50$  Hz Frequency. To achieve this aim we shall do the following procedures:

- Designing the mathematical model which shows all design calculations and the electromagnetism of the deep-well induction motor of a voltage of  $f=150$  Hz frequency cases:

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a) when changing the quality of the squirrel-cage metal (copper, aluminum)

b) when changing the induction in the air-gap .

c) when changing the height of the slot close.

- Finding the suggested algorithm for the above - mentioned model showing the flowchart the calculation processes for the mentioned stages.
  - Executing a program in the computer by using one of the program languages of high standard to get the design results for all previous cases.
- Comparing the results and defining the efficiency values, the slip and the critical slip and defining the percentage of the start moment and the maximum moment to the nominal moment for each case in study.

For the paper Arabic Language see the pages ( ).