

1. $\vec{OM} = r\hat{r}$
 $\vec{OM} = r\hat{r} + z\hat{k}$
 $\vec{OM} = (r-r\hat{r})\hat{r} + (2r\hat{r} + r\hat{r})\hat{r}$
 $\rho = \frac{|\vec{M}|^2}{|\vec{M} \cdot \vec{M}|}$ (5+)

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2. $\vec{A} = x\hat{i} + y\hat{j} + z\hat{k}$
 $\cos \alpha = \frac{x}{|\vec{A}|}$
 $\cos \beta = \frac{y}{|\vec{A}|}$
 $\cos \gamma = \frac{z}{|\vec{A}|}$
 $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = \frac{x^2 + y^2 + z^2}{|\vec{A}|^2} = 1$ (5+)

3. $\vec{OM} = r\hat{r}$
 $\vec{OM} = r\hat{r} + r\hat{r} + r\hat{r}$
 $r = 5$ $\hat{r} = 0$ $\hat{r} = 0$
 $\vec{OM} = 5\hat{i} + 5\hat{j} + 5\hat{k}$
 $|\vec{OM}| = \sqrt{25+25+25} = \sqrt{75}$ (5+)

4. $\vec{a} \cdot (\vec{b} + \vec{c}) = |\vec{a}| \cdot \text{Proj}(\vec{b} + \vec{c})$
 $= |\vec{a}| (\text{Proj } \vec{b} + \text{Proj } \vec{c})$
 $= |\vec{a}| \text{Proj } \vec{b} + |\vec{a}| \text{Proj } \vec{c}$
 $= \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$ (5+)

5. $x = 2 \cos t$
 $y = 3 \sin t$
 $\frac{x^2}{4} + \frac{y^2}{9} = 1$ (5+)

6. $\hat{A} \hat{B} \hat{C} = \hat{B} \hat{C} \hat{A} = \hat{C} \hat{A} \hat{B}$
 $\frac{1}{2} |\vec{A} \times \vec{B}| |\vec{C}| = \frac{1}{2} |\vec{B} \times \vec{C}| |\vec{A}| = \frac{1}{2} |\vec{C} \times \vec{A}| |\vec{B}|$
 $= |\vec{A}| |\vec{B}| |\vec{C}| \sin A = |\vec{B}| |\vec{C}| |\vec{A}| \sin B = |\vec{C}| |\vec{A}| |\vec{B}| \sin C$ (5+)

7. $x = x - y$ $\frac{x^2 + y^2}{x^2 - y^2}$
 $y = y + x$ $\frac{x^2 + y^2}{x^2 - y^2}$
 $\dot{x} = -2 \sin t$
 $\dot{y} = 3 \cos t$
 $\ddot{x} = -2 \cos t$
 $\ddot{y} = -3 \sin t$
 ... (5+)

8. $c \cdot a \sin B = b \sin C = b c \sin A$
 $\frac{\sin A}{a} = \frac{\sin B}{b} = \frac{\sin C}{c}$
 $\vec{OM} = \vec{r} \hat{r}$
 $\vec{OM} = \vec{r} \hat{r}$ (5+)

$$-2y \cos x - 2x^2 + y \cos x$$

$$\phi = \int p dx + \int q dy + r dz$$

$$\text{rot } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ p & q & r \end{vmatrix}$$

$$\vec{F} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

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$$\vec{B} = \vec{T} \cdot \vec{M}$$

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